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# AdaptiveNet: Post-deployment Neural Architecture Adaptation for Diverse Edge Environments

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# AI is Transforming the World, with Cloud + Edge



## ChatGPT

  
Pathways



### Cloud AI

multi-domain, multi-task, general-purpose services



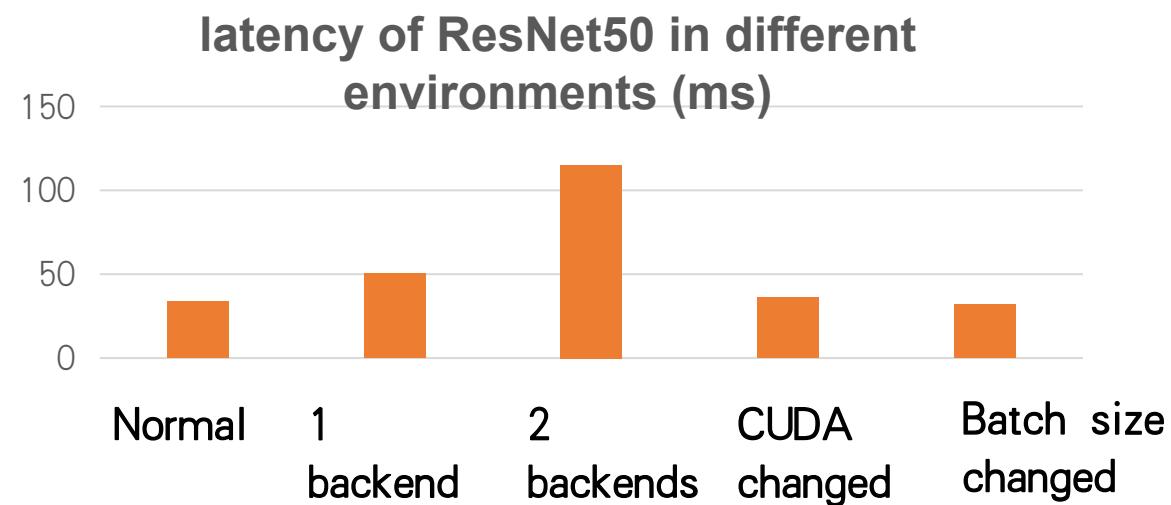
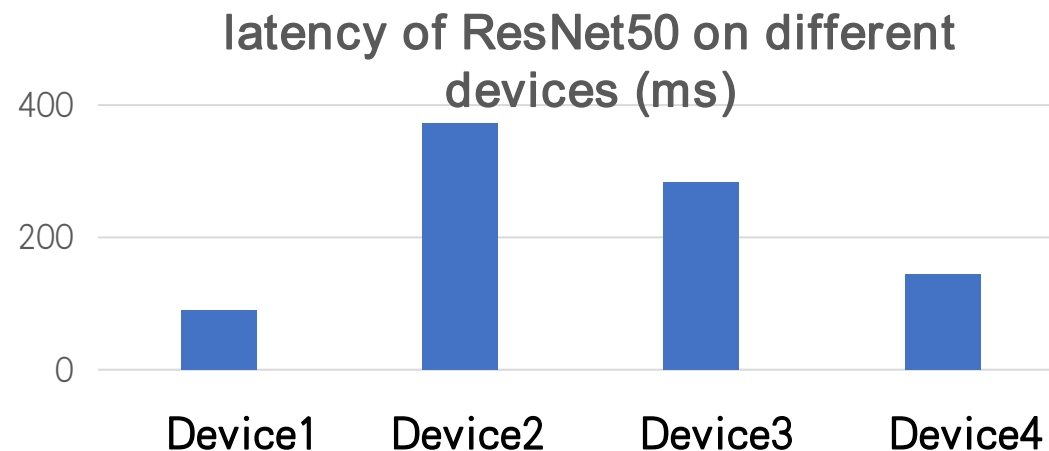
### Edge AI

Domain-specific, real-time, privacy-sensitive applications

# Environment Diversity is a Main Challenge in Edge AI

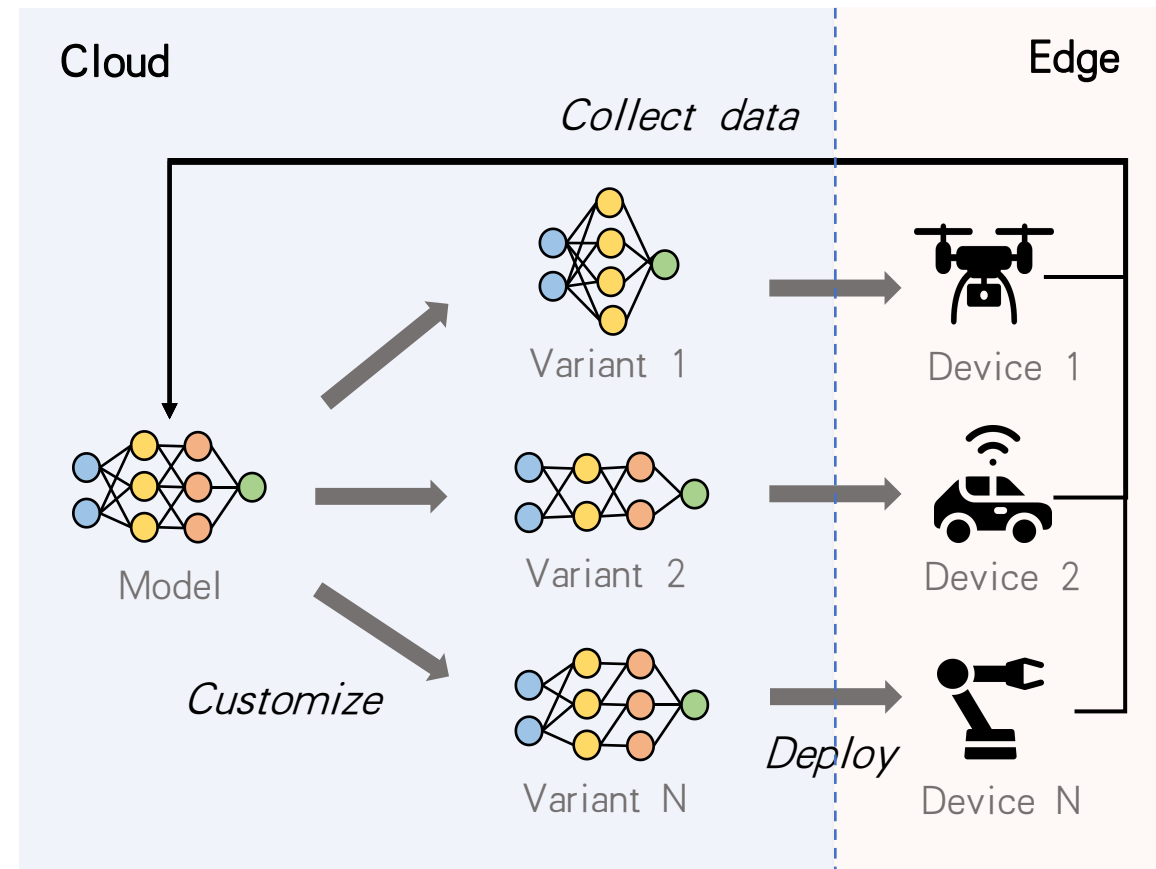
- **Device diversity is a main challenge**
  - a) hardware diversity
  - b) Intra-device diversity (backend number, software version, temperature)
  - c) data distribution diversity
- DNNs are expected to meet certain constant latency requirements.

***Challenge: Generate models for diverse edge environments.***



# Conventional: Pre-deployment Model Generation

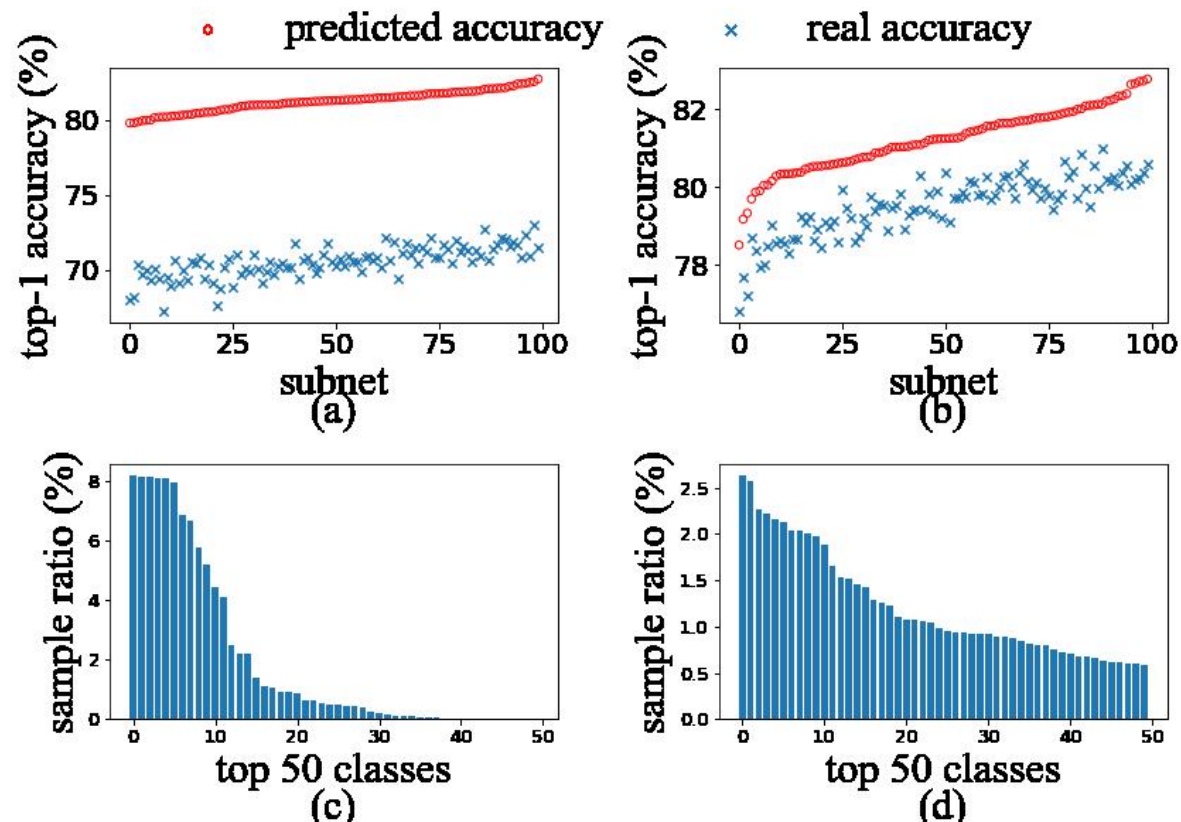
- **Most popular techniques:** Neural Architecture Search (NAS), Model Pruning, etc.
- **Limitations:**
  1. **Requires collecting privacy information** about computational resources, runtime conditions, data distribution, etc.
  2. **High maintenance cost.** Less practical in many edge/mobile scenarios where the model execution environments may be very diverse and dynamic.



# Conventional: Pre-deployment On-cloud Model Generation

## 3. Modeling the edge environment may be difficult.

- The cloud-based model generation relies on *accuracy and latency predictors*
- The unified accuracy predictor may not perform well for edge devices with *data distribution shifts*.

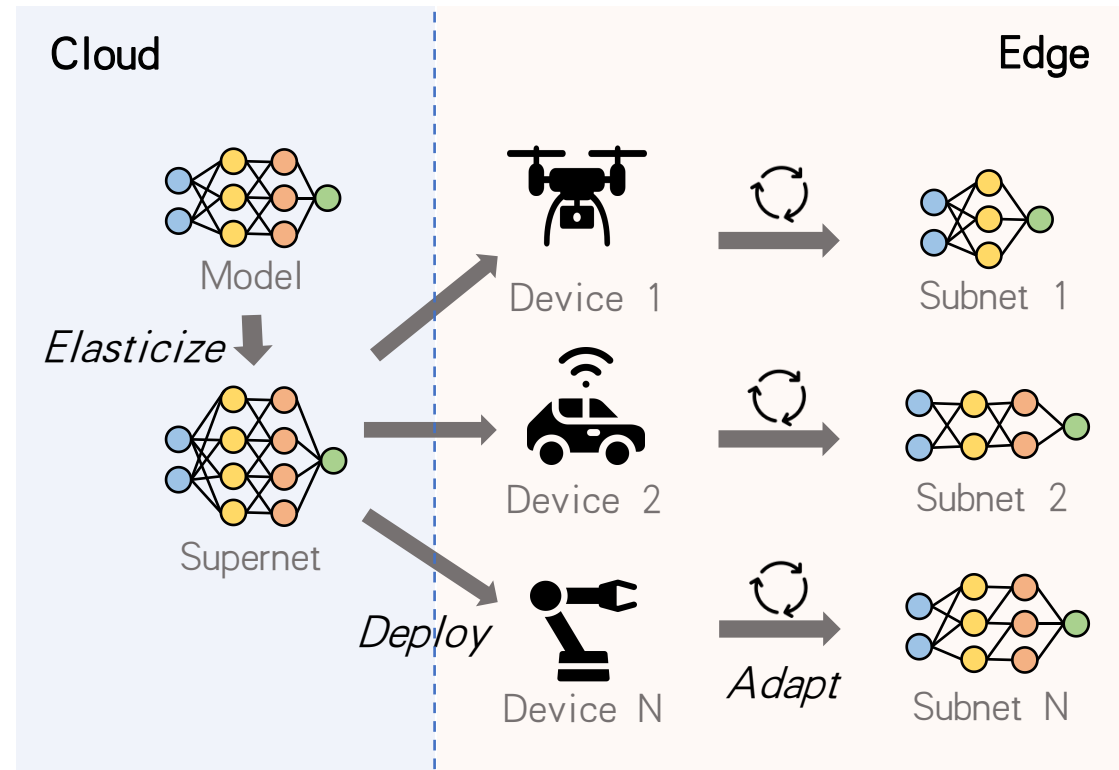


Performance of accuracy predictor on non-iid edge data. The edge data is simulated with Dirichlet distributions with (a)  $\alpha=0.005$  and (b)  $\alpha=0.1$ . The sample ratios of top-50 classes are shown in (c) and (d).

# Solution: Post-deployment Neural Architecture Adaptation

## Benefits:

- Directly evaluate the a given DNN ***without accuracy predictor***, which is more precise.
- A plug-and-play process, ***reduces the computation overhead*** of the cloud.
- ***Protects user privacy.***



**Related work in mobile community:** on-device model scaling (NestDNN, LegoDNN, etc.):

***Limited model space; Still relying on performance predictors.***

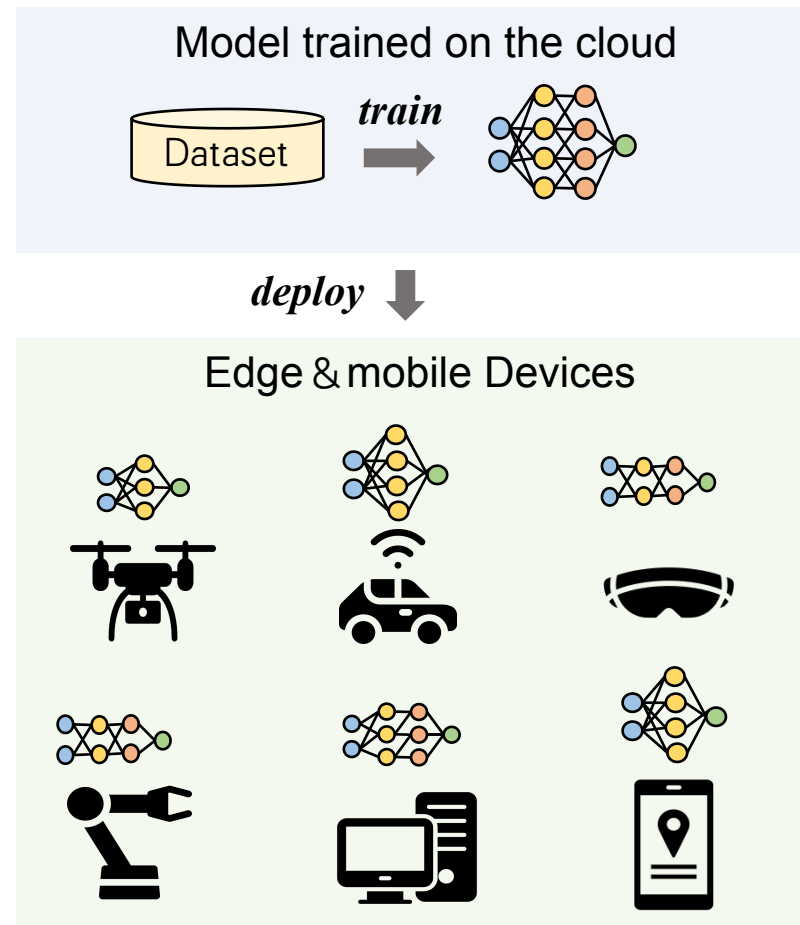
# Challenges

**Generating the model search space for edge devices is difficult.**

- The search space should be **large** and **flexible** enough.
- Should contain **high-quality candidate models** for edge devices.

**The model performance evaluation process can be time-consuming at the edge.**

- **Limited computing resources** and tight deadline of model initialization.
- The edge environment is **dynamic**.



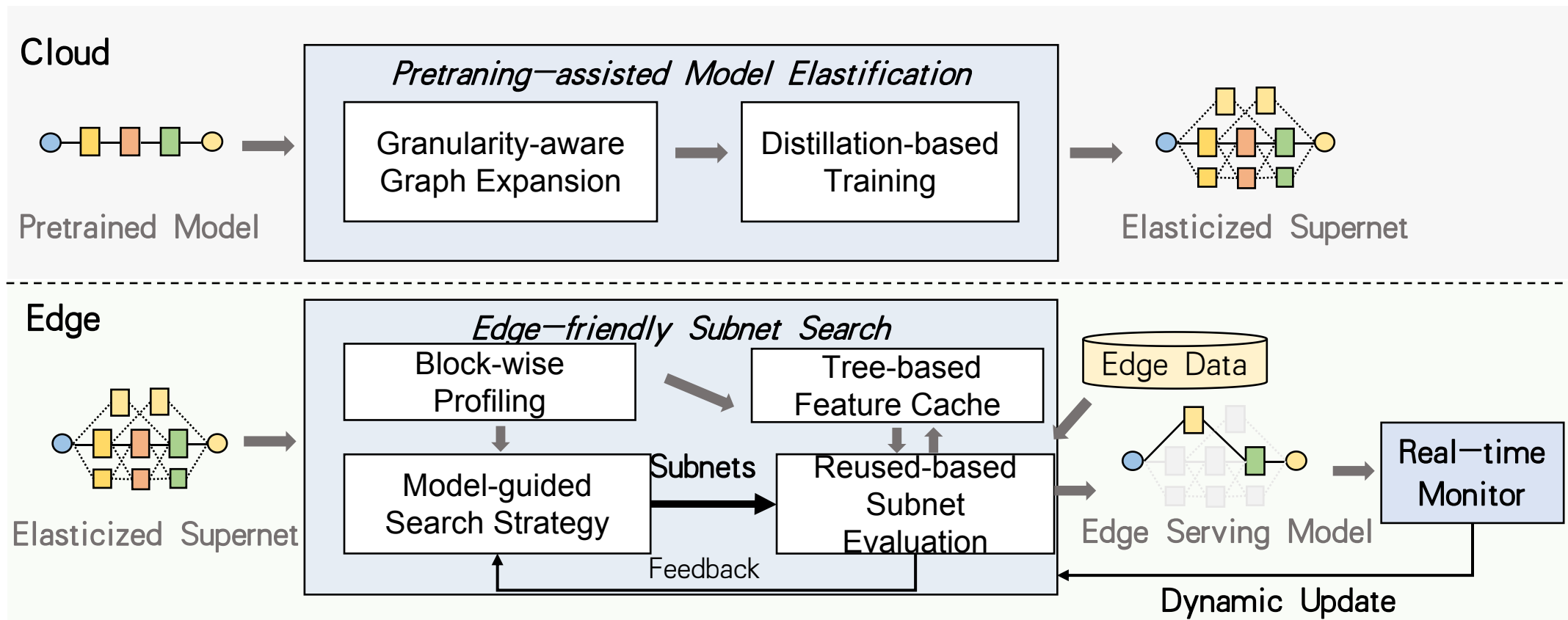


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# Method



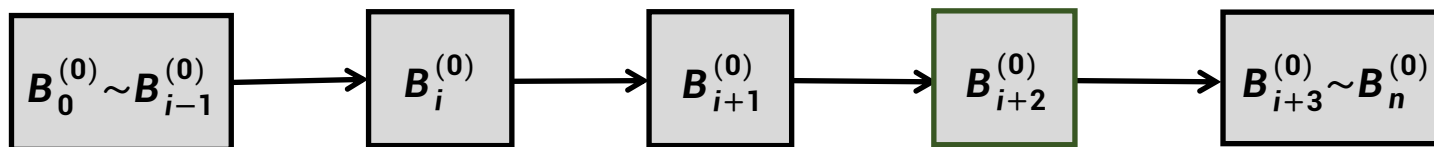
# AdaptiveNet: System Design



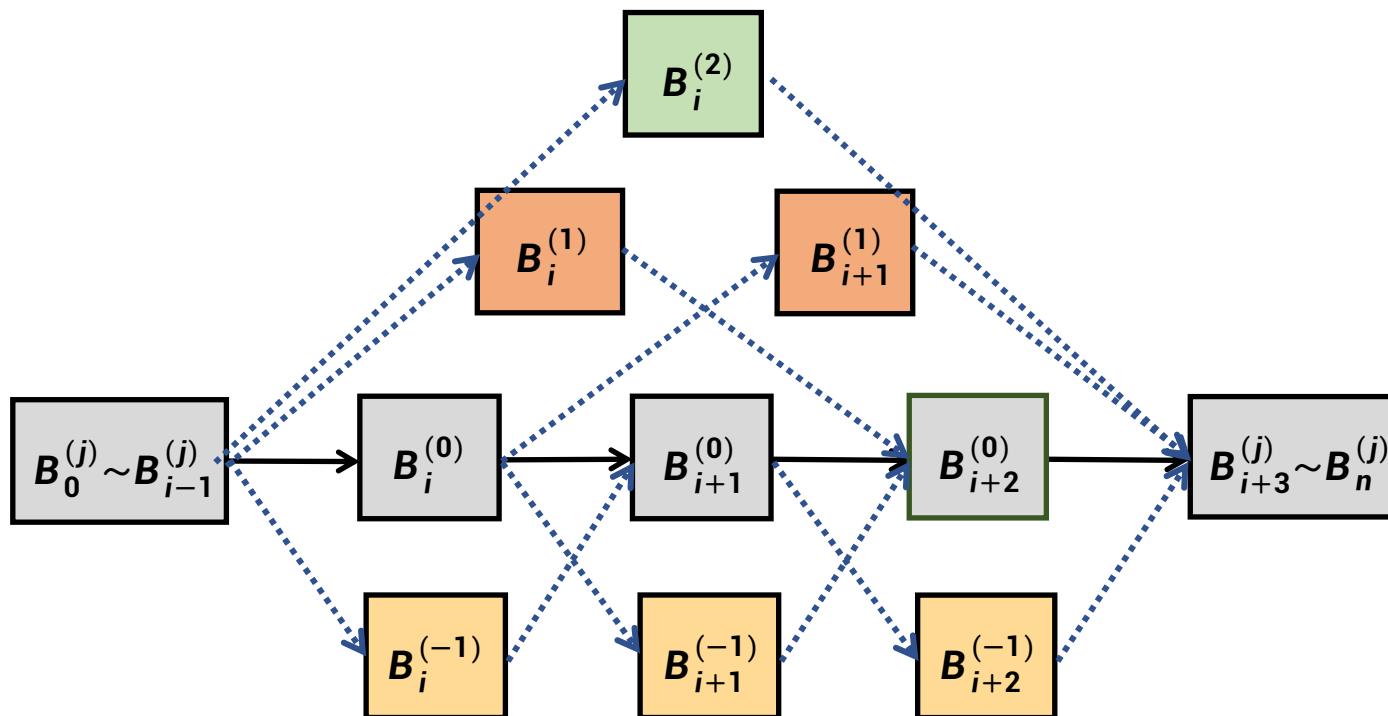
The architecture overview of AdaptiveNet

# Cloud Stage: Graph Expansion

1. Given an arbitrary pre-trained DNN, We discover the repeating **basic blocks** ( $B_0^{(0)} \sim B_n^{(0)}$ ) in the DNN.

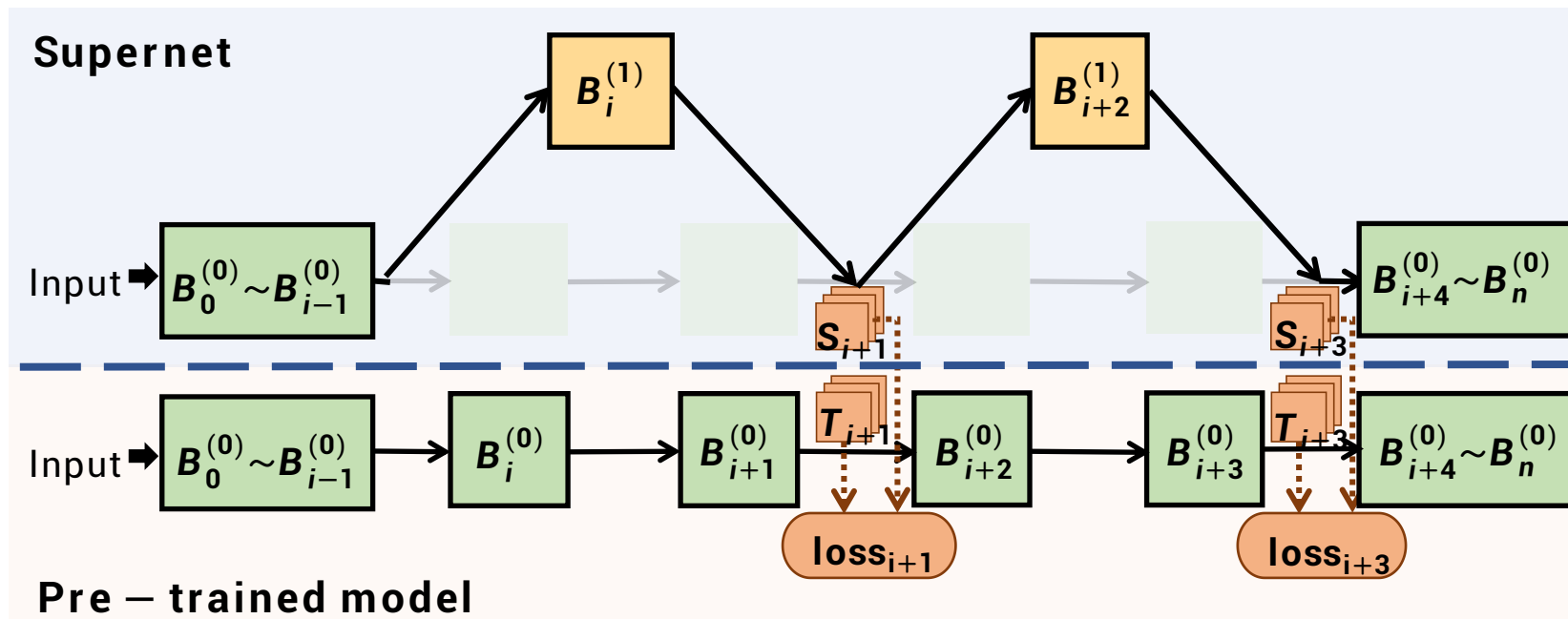


# Cloud Stage: Graph Expansion



2. We convert the given pre-trained DNN into a **supernet** by adding **merged blocks** ( $B_i^{(1)}$ ,  $B_i^{(2)}$ ) and **pruned blocks** ( $B_i^{(-1)}$ ). The **supernet** encompasses a large search space of **subnets**.

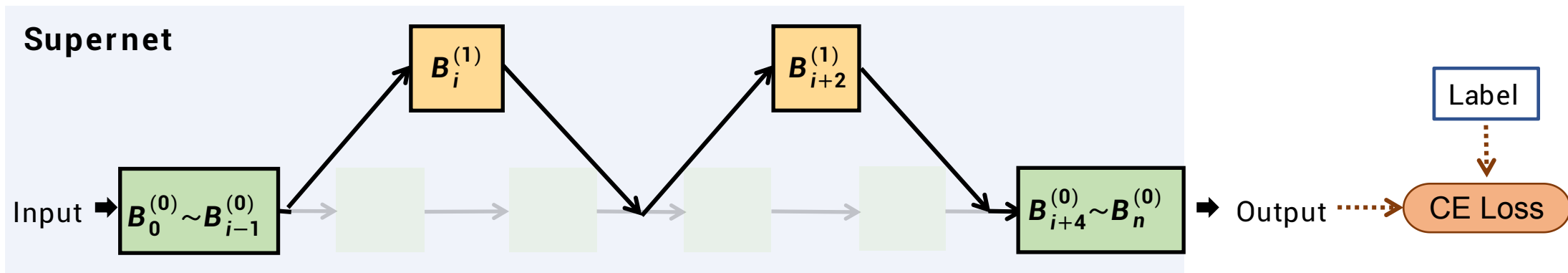
# Cloud Stage: Distillation-based Training



## ***Branch distillation phase:***

- Adopt feature-based knowledge distillation (Pre-trained model as the teacher).
- In each iteration, randomly sample a subnet from the supernet and use the pre-trained model as the teacher model to train the new branches in the subnet.

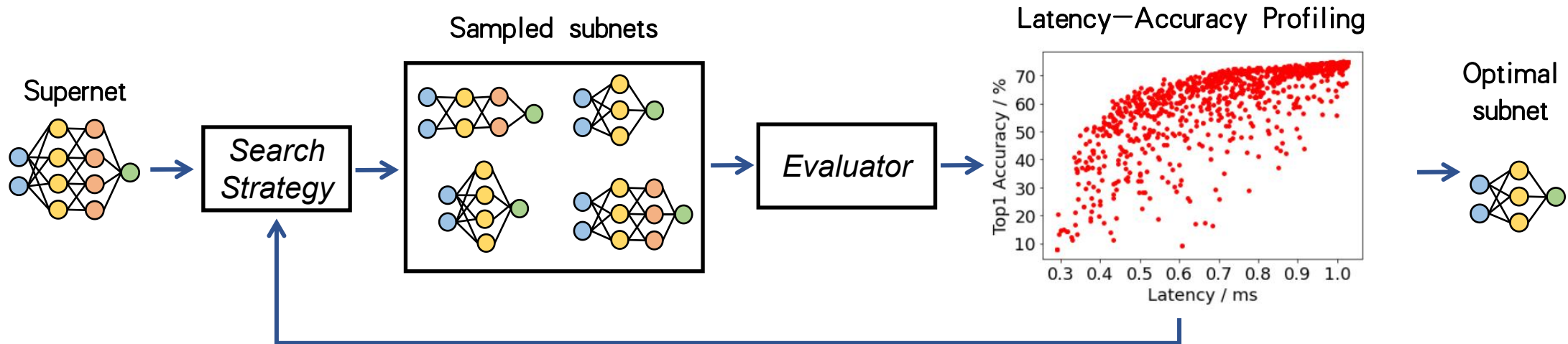
# Cloud Stage: Distillation-based Training



## ***Further tuning phase:***

- Further train the supernet using labelled data.
- In each iteration, randomly sample a subnet and forward a batch of samples, compute the Cross-Entropy loss and update the parameters of the new branches.

# Edge Stage: Overview



- **Edge Stage** is to obtain the optimal architecture adaptively in the target environment by searching the subnet space.
- **Using a normal search method as in NAS can cost more than 10 hours on edge devices.** Most of the searching time is spent on **evaluating the subnets**.

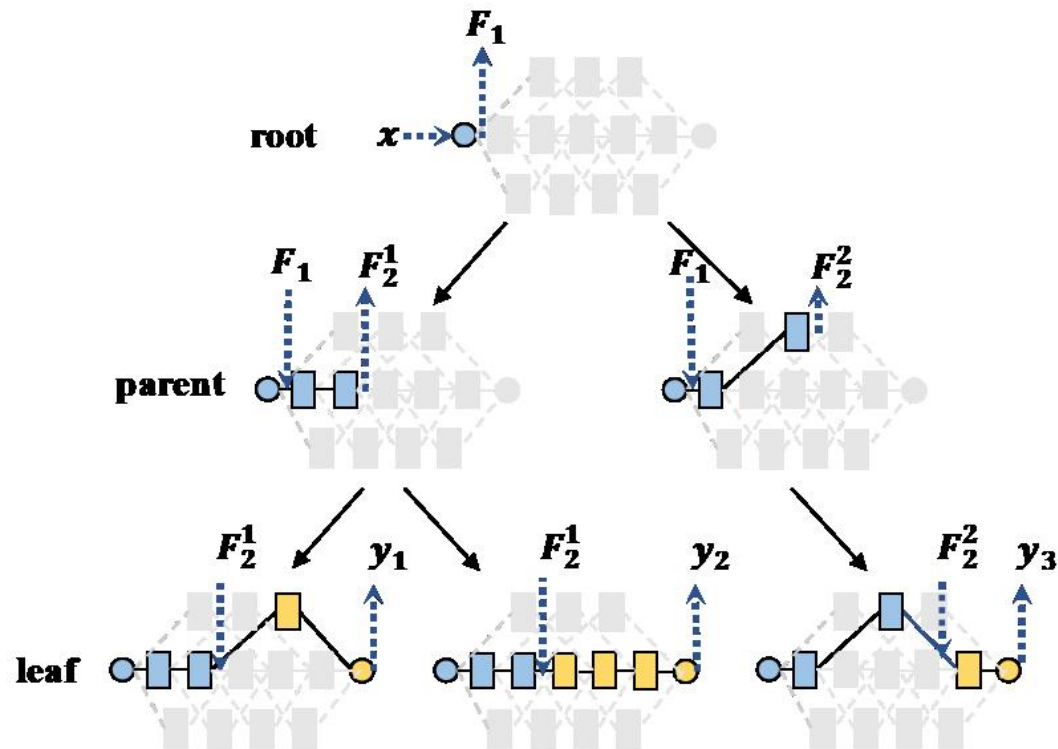
# Edge Stage: Search Strategy

Taking the example of **Genetic Algorithm (GA)** - based search strategy:

1. Build **Latency Table**  $T = \{t_i^j\}$  ( $t_i^j$  is the latency of  $B_i^j$ ). Thus, the latency of a chosen subnet is the sum of all its blocks.
2. Generate the **initial candidate subnets** by randomly sampling a group of subnets whose latencies are near the **latency budget**.
3. In each iteration, mutate subnets by replacing branches. (**Make sure the mutated subnets are also near the latency budget**).

# Edge Stage: Evaluator

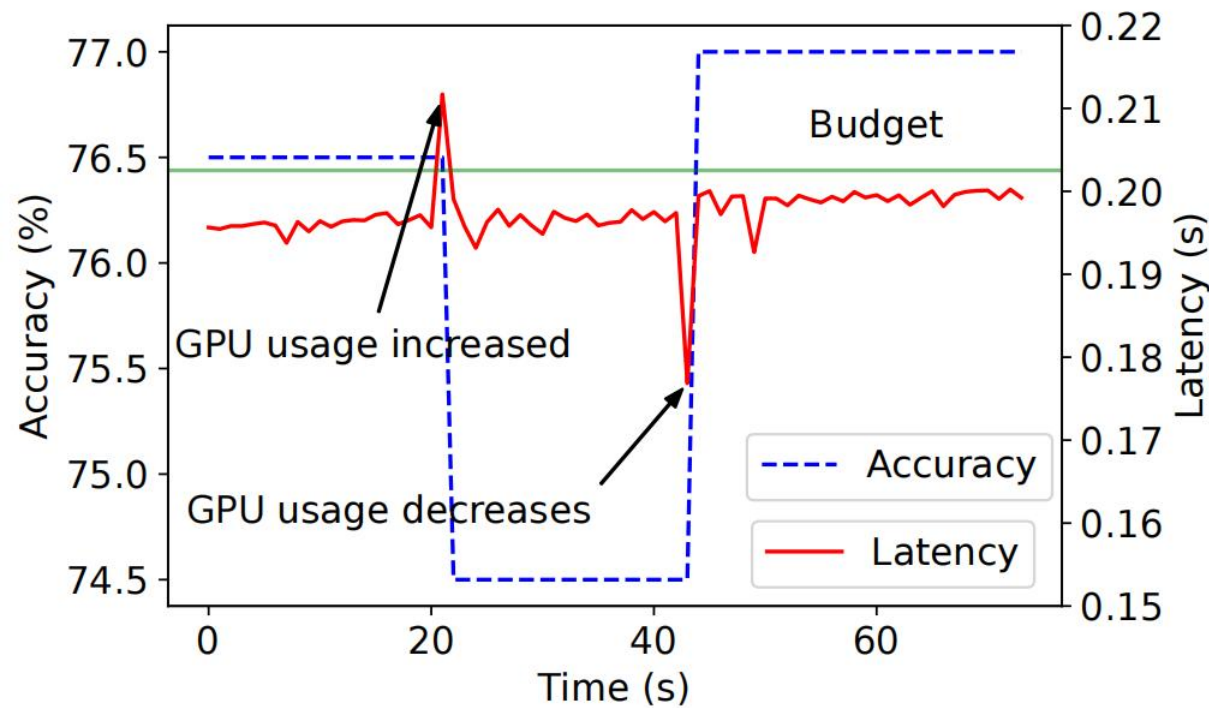
- In each iteration, we usually need to evaluate ***hundreds of candidate subnets*** with the edge data to find the most accurate ones.
- The candidate subnets usually share common prefix substructures, so we can reuse common intermediate features across subnets.
- We introduce a ***tree-based feature cache*** to schedule the evaluation (Right Figure).





## Edge Stage: Dynamic Model Update

- After searching, the subnets achieving the highest accuracy at different levels of latency are saved.
- AdaptiveNet dynamically pages in and pages out alternative blocks when the environment changes.





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# Evaluation

# Evaluation: Experimental Setup

## 1. Edge devices:

- Android Smartphone (Xiaomi 12) with Snapdragon 8 Gen 1 CPU and 8 GB memory
- Jetson Nano with 4 GB memory
- Edge server with NVIDIA 3090 Ti with 24 GB GPU memory

## 2. Baselines:

- LegoDNN [1]: a pruning based, block-grained technique for model scaling
- Slimmable Networks [2], FlexDNN [3], SkipNet [4]: dynamic neural networks with flexible widths, depths, and layers.

## 3. Tasks, Models, and Datasets:

Task	Model	Dataset
Image classification	MobileNetV2, ResNet.	ImageNet2012
Object detection	EfficientDet	COCO2017
Semantic segmentation	FPN	CamVid

[1] Han et al. LegoDNN: Block-Grained Scaling of Deep Neural Networks for Mobile Vision. (MobiCom 2021)

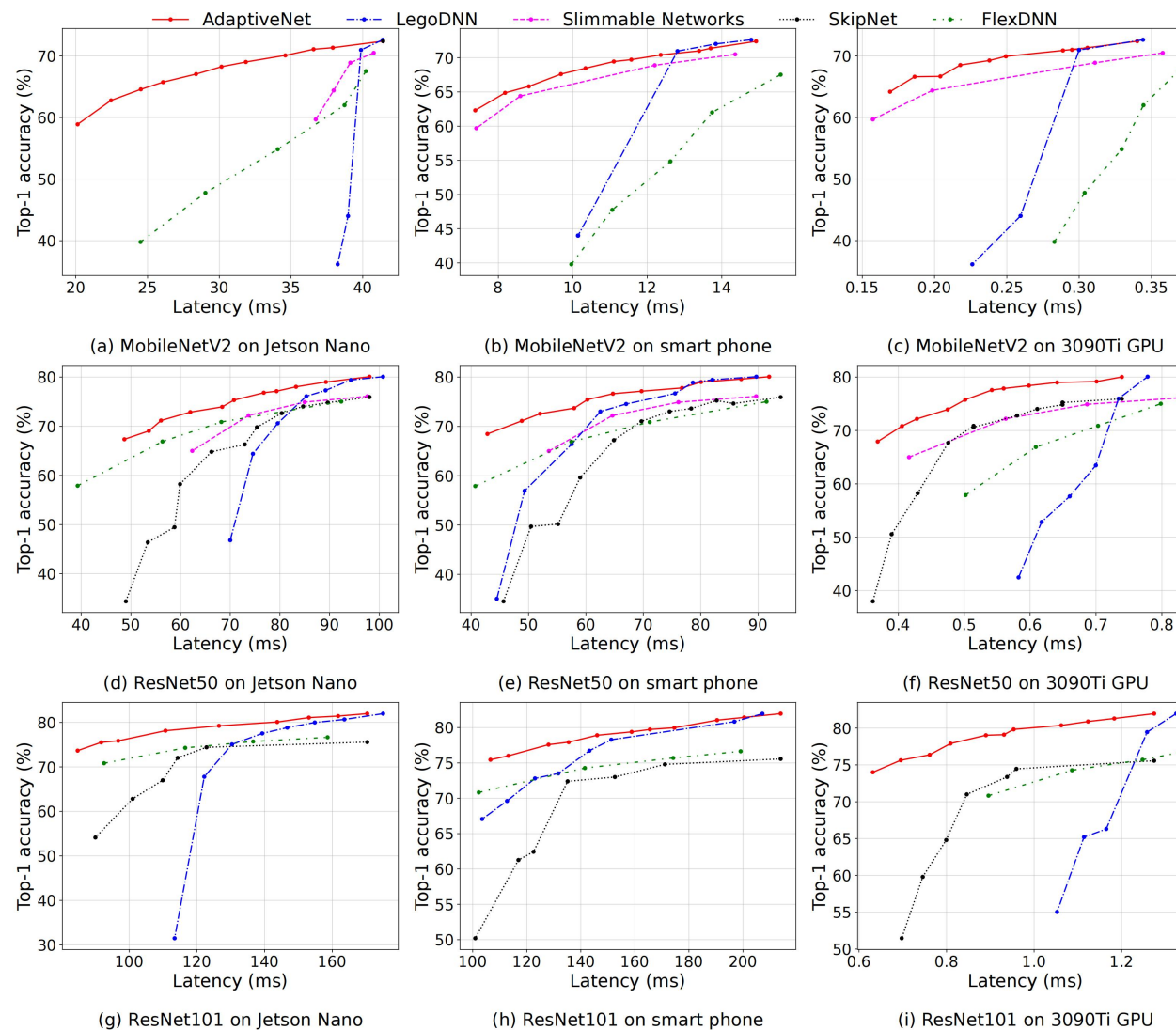
[2] Yu et al. Slimmable Neural Networks. (ICLR 2019)

[3] Fang et al. FlexDNN: Input-Adaptive On-Device Deep Learning for Efficient Mobile Vision. (SEC 2020).

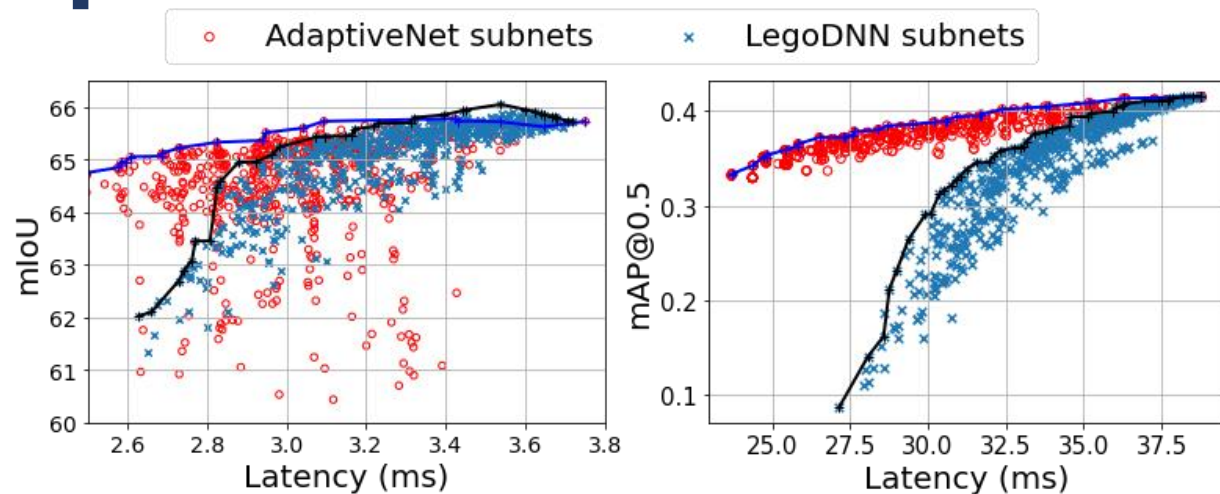
[4] Wang et al. SkipNet: Learning Dynamic Routing in Convolutional Networks. (ECCV 2019).

# Evaluation: Model Scaling

- AdaptiveNet achieves higher accuracy than baseline approaches **at almost every latency budget**.
- Increases accuracy by 10.44% and 28.03% on average compared to LegoDNN with 90% and 70% latency budget respectively.
- AdaptiveNet outperforms the baseline models more at a lower latency budget thanks to the merging blocks.



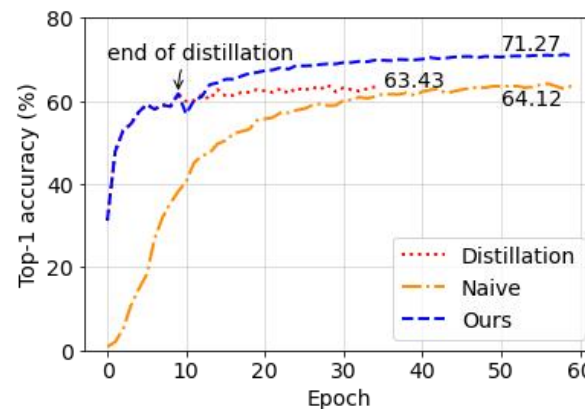
# Evaluation: Model Scaling and Training Efficiency



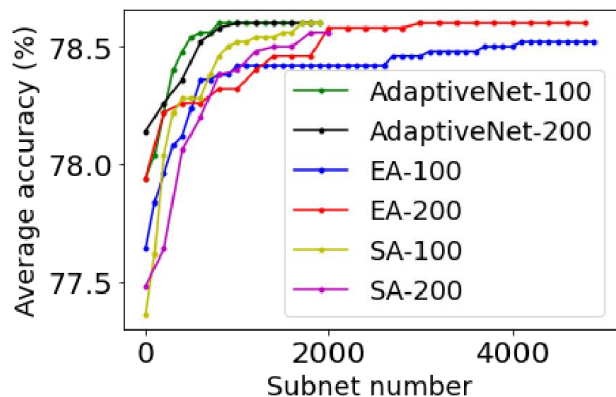
(a) Semantic Segmentation

(b) Object Detection

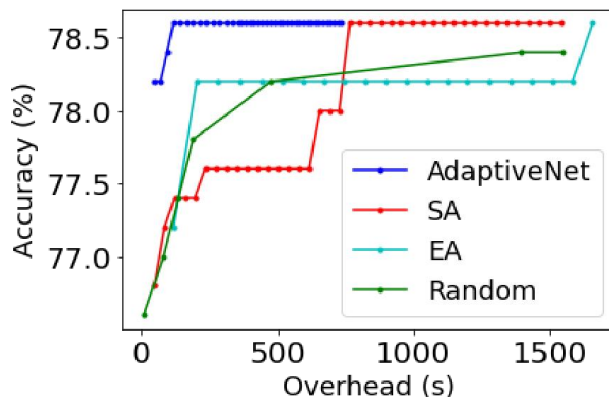
Quality of models generated for detection and segmentation tasks.



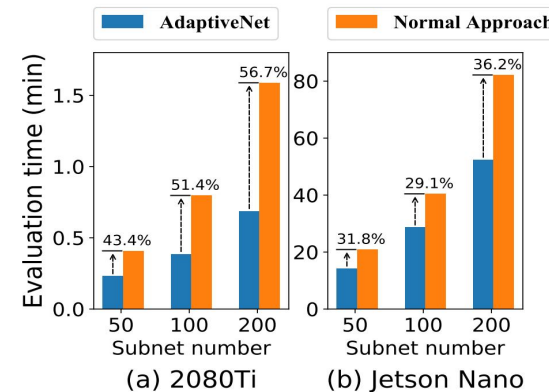
Training efficiency of on-cloud elastification.



Optimal accuracy achieved with different num of subnets.



Optimal accuracy achieved with different search time.



Speed of evaluating a group of subnets.

# Conclusion and Outlook

- AdaptiveNet is a novel approach for **on-device, post deployment, and environment-aware** model architecture generation.
- It is an end-to-end system equipped with **on-cloud model elastification** and **on-device model adaptation**.
- Future work
  - Generalize AdaptiveNet to **pre-trained/foundation models**.
  - Design supernet that can adapt to **edge data distributions**.
  - Generate subnets that can deal with **domain-specific tasks** directly.

Open sourced: <https://github.com/wenh18/AdaptiveNet>

# Thanks !

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