

BatMobility 🦇 :

Towards Flying Without Seeing for Autonomous Drones

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Autonomous drones enable exciting applications...



Extending wireless networks



Automated cargo delivery

Rely on optical sensors for spatial awareness

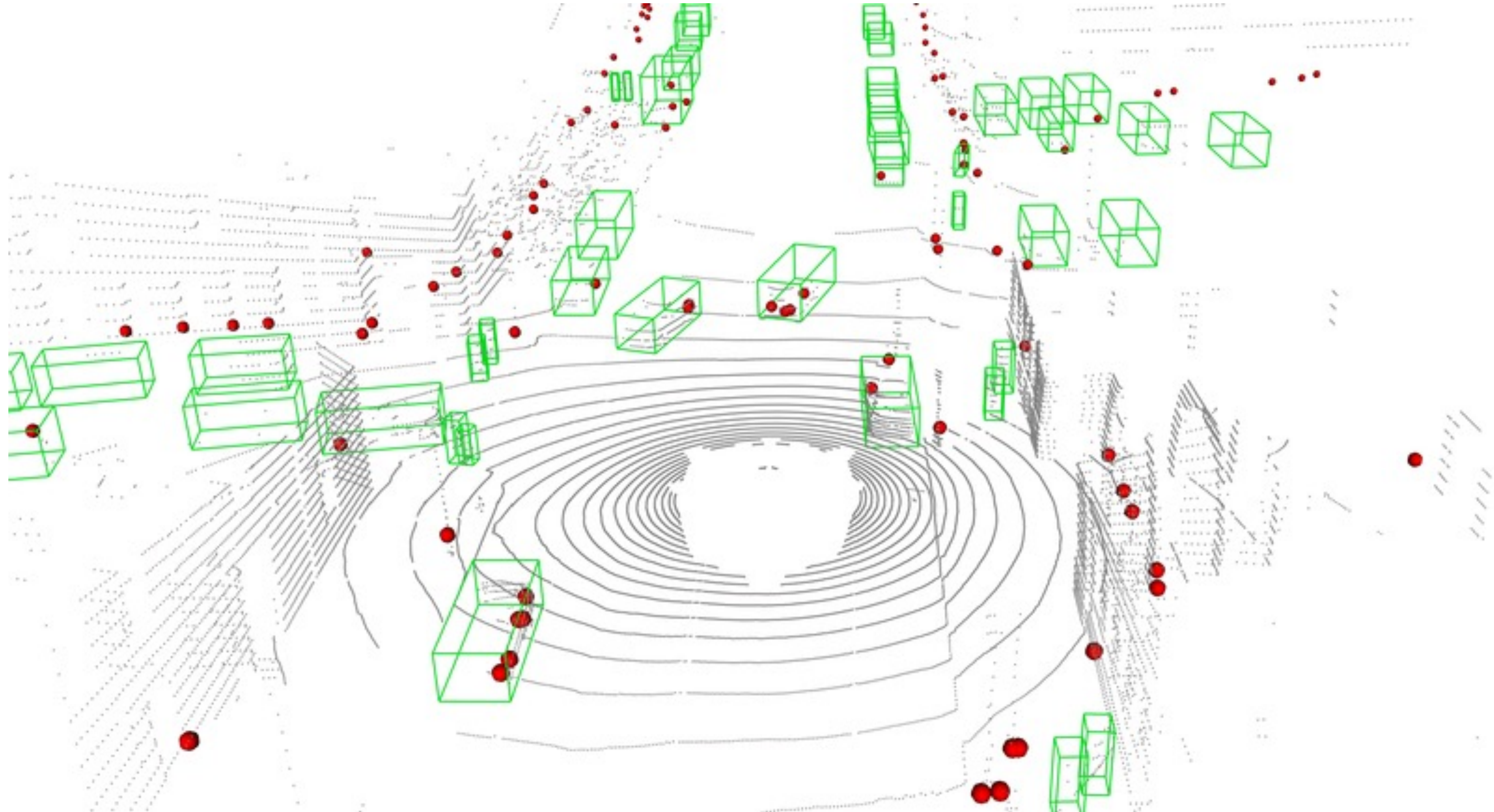


Surveillance and Inspection



Warehouse inventory management

Why the hate on radar?



Yes, radar has low resolution. But...

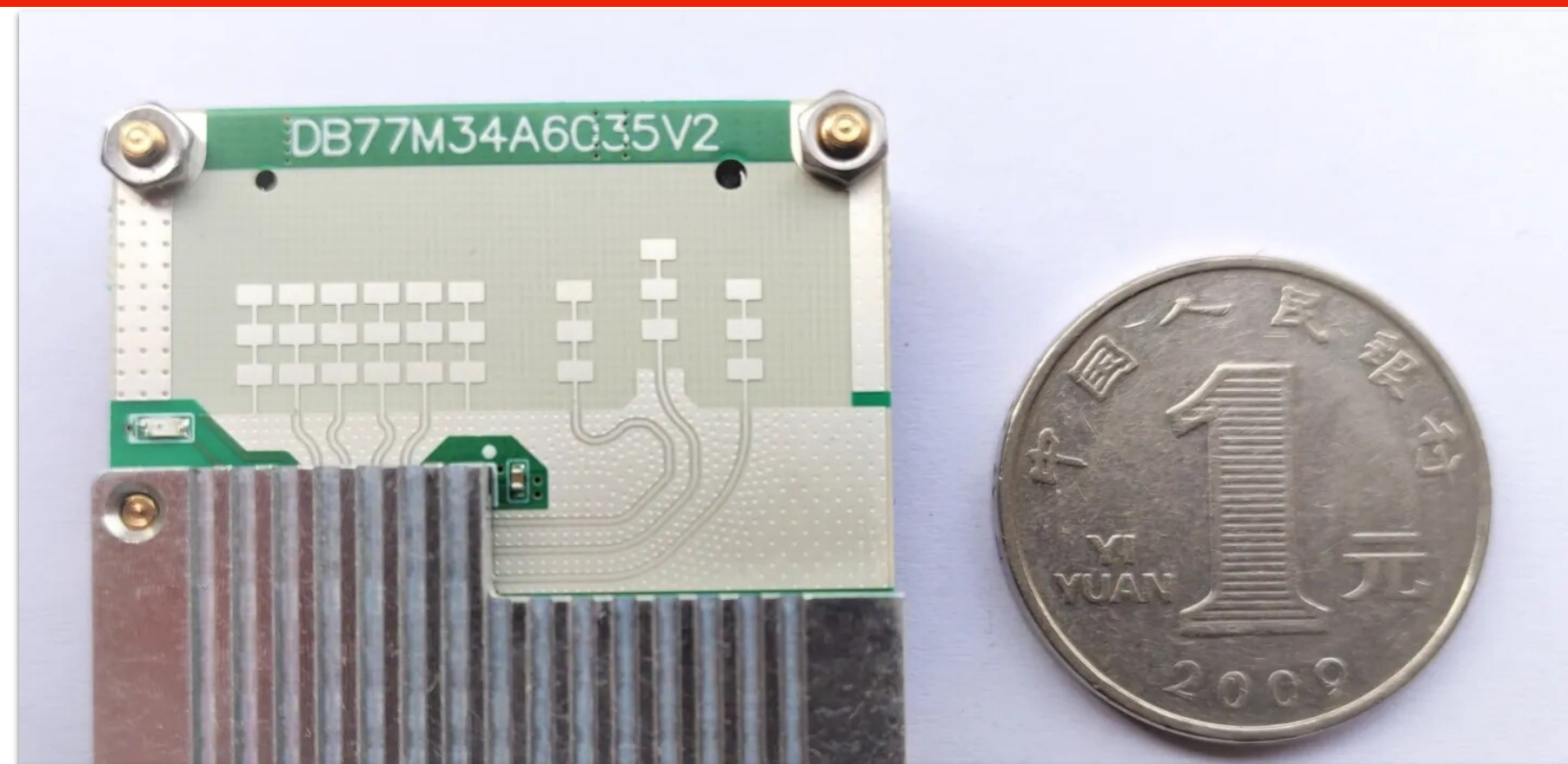


Penetrates Fog, Smoke, Dust



Invariant to Light

Seems like a good fit for autonomous drones 🤔

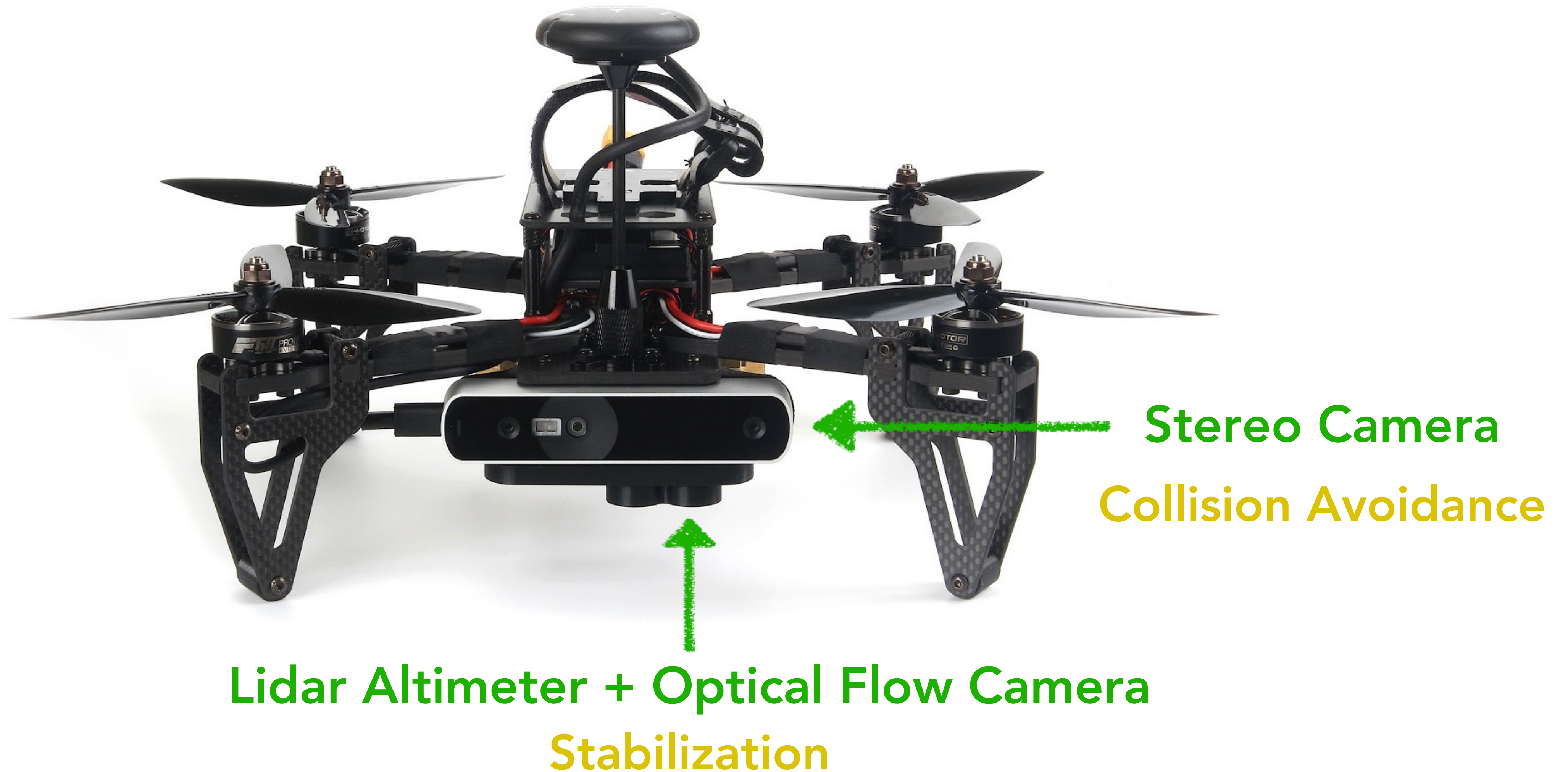


Cheap and Small

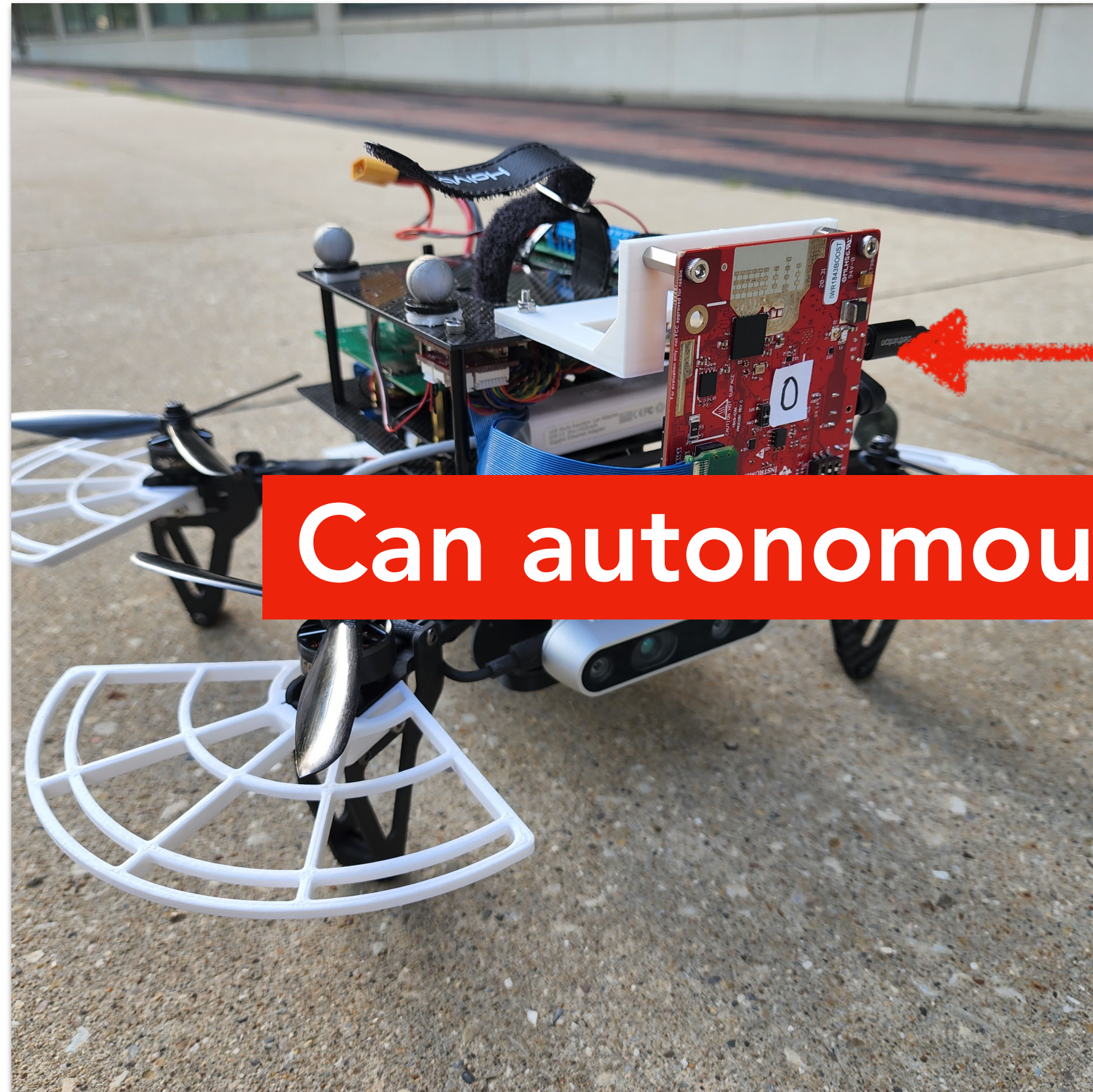


Long Range

Radar is all you need?



Radar is all you need?



Off-the-shelf
Radars



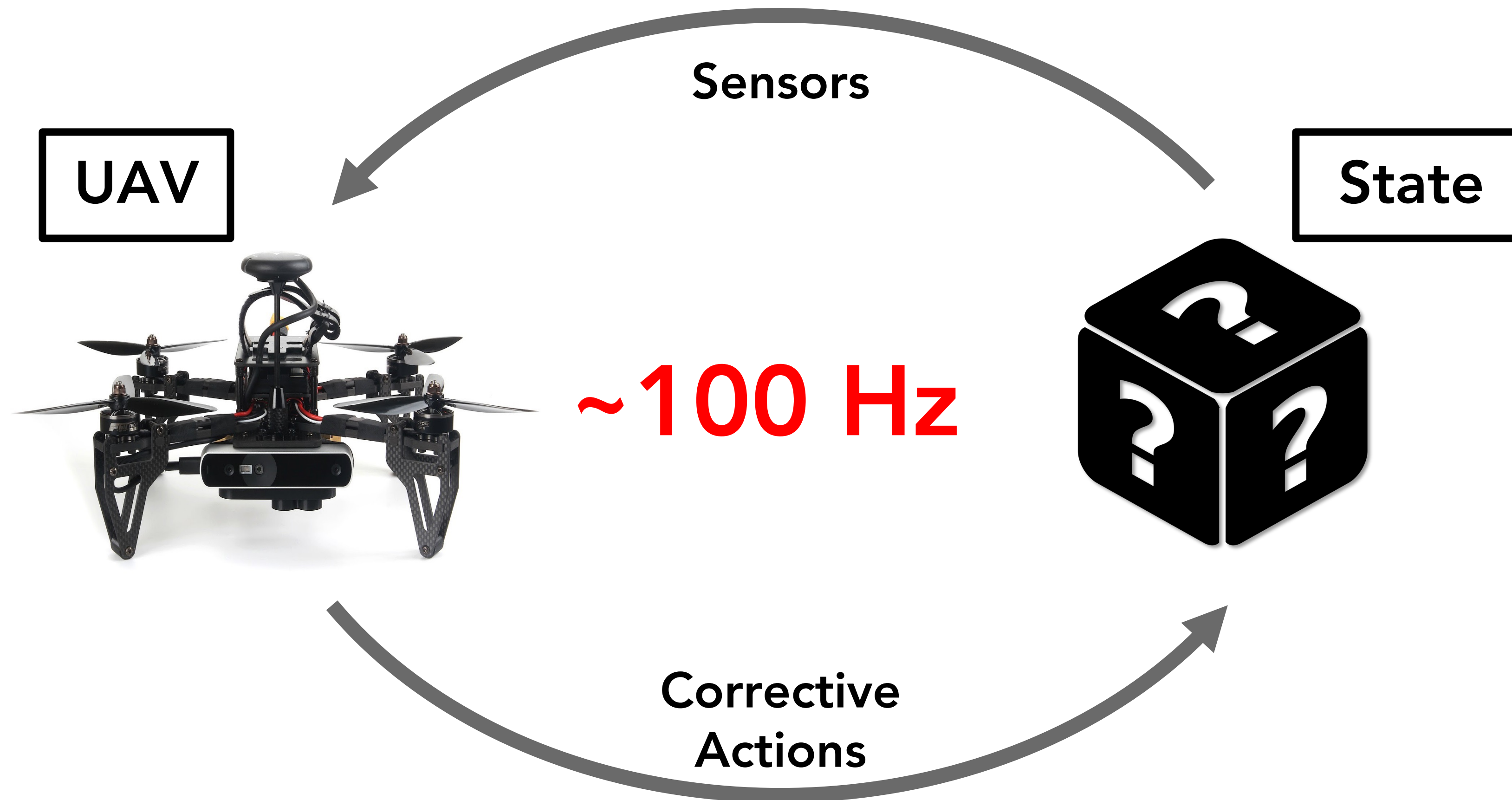
Can autonomous drones fly without seeing?

Why is flying hard?

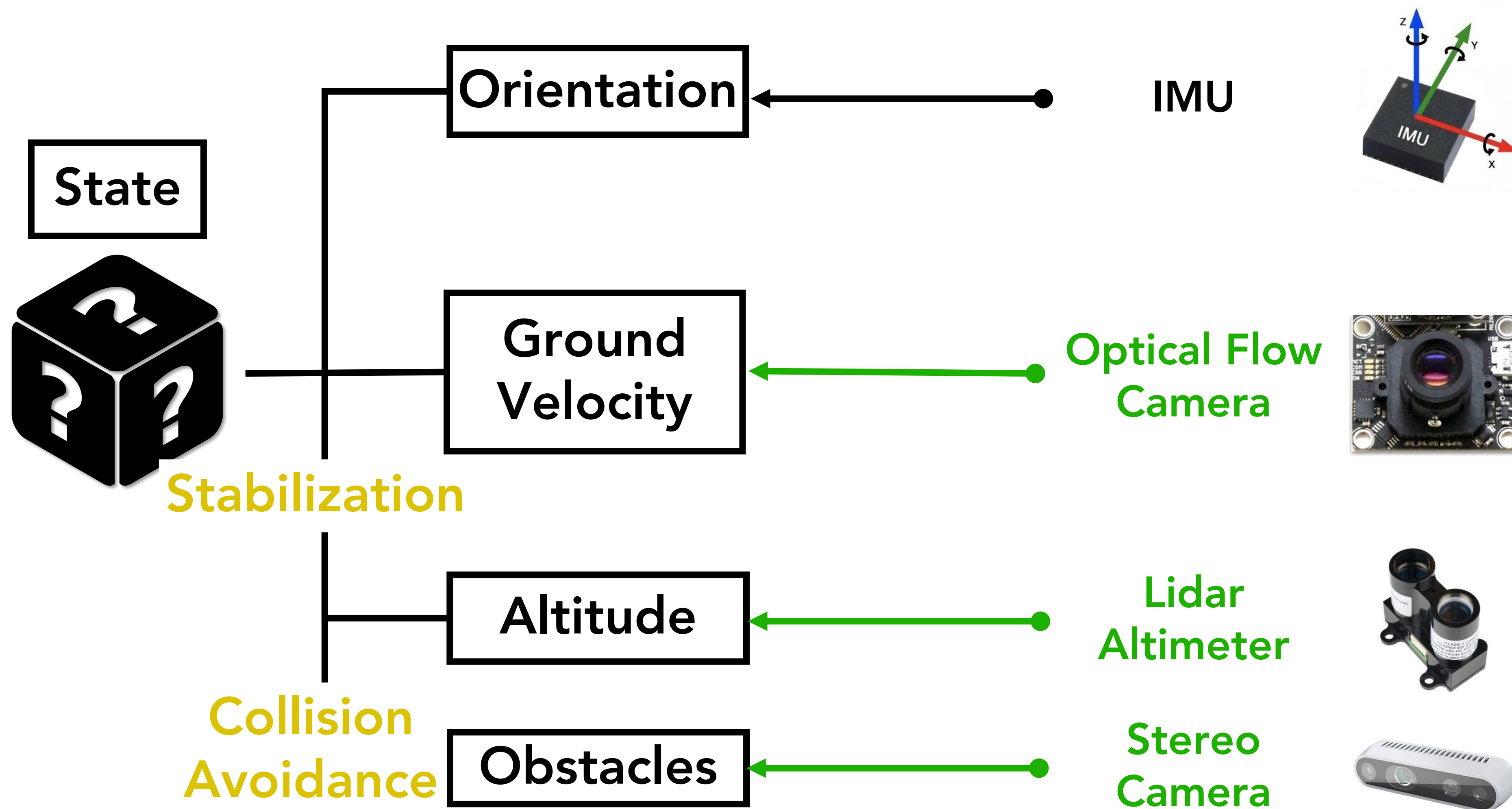


Drones are inherently unstable

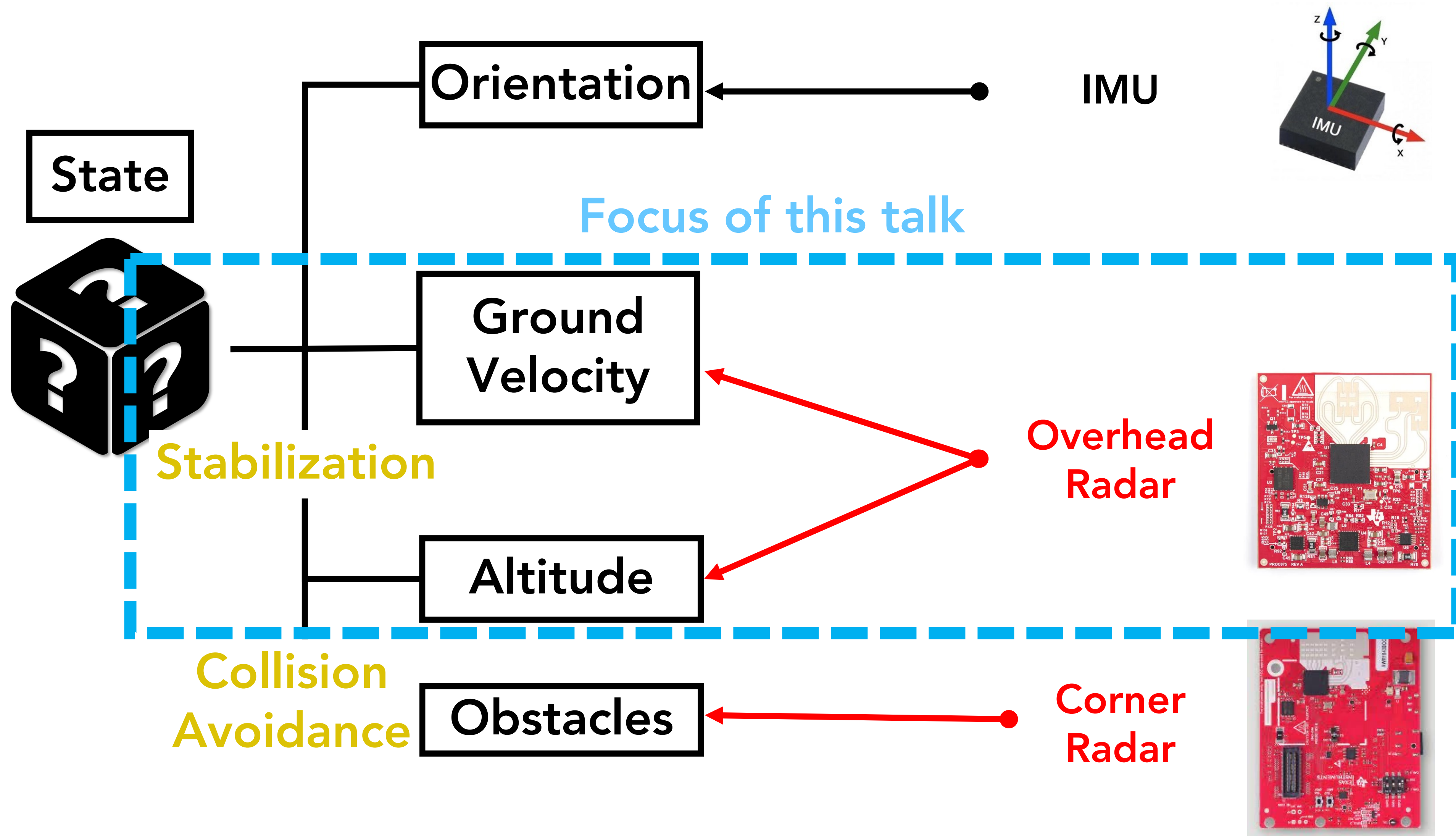
Why is flying hard?



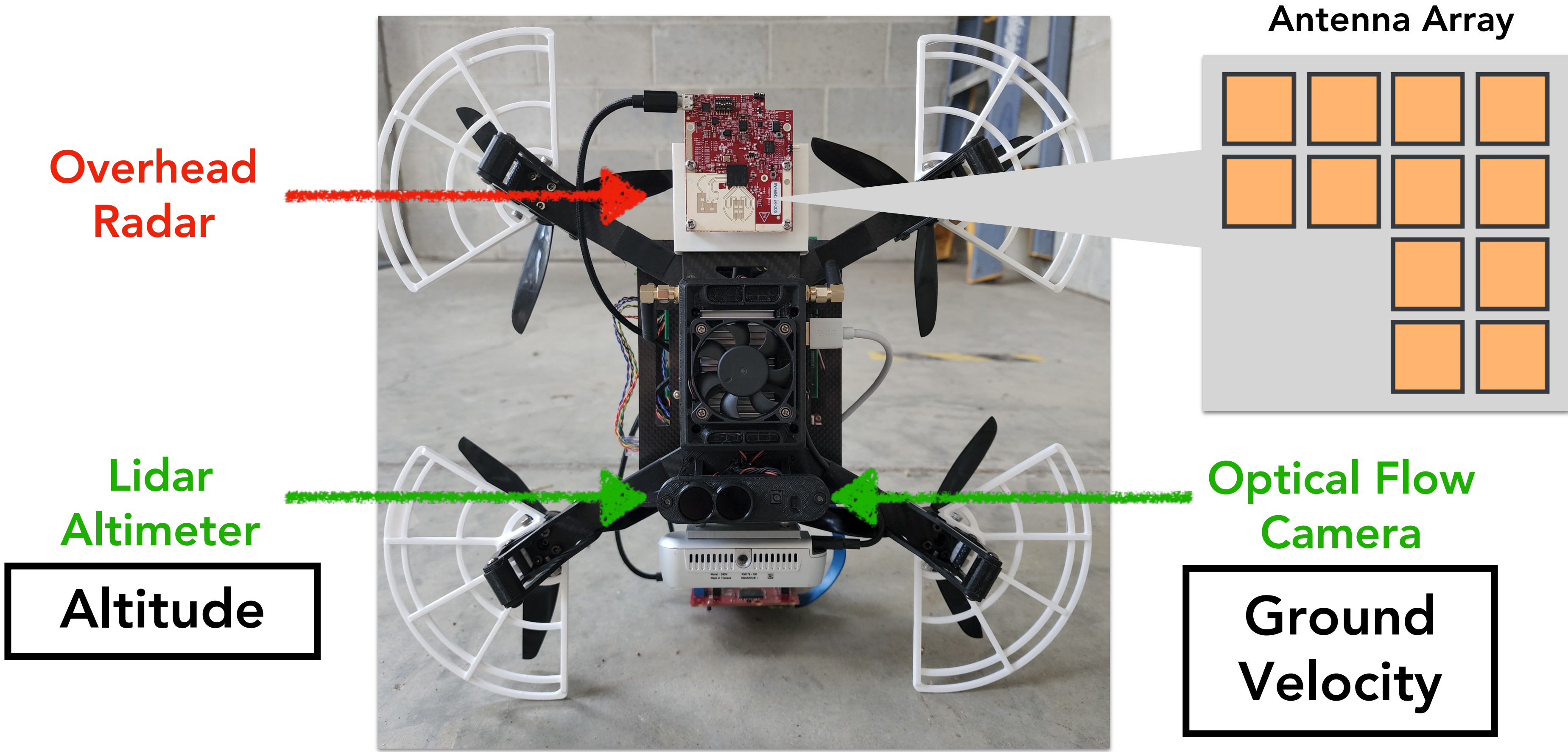
Why is flying hard?



BatMobility Overview



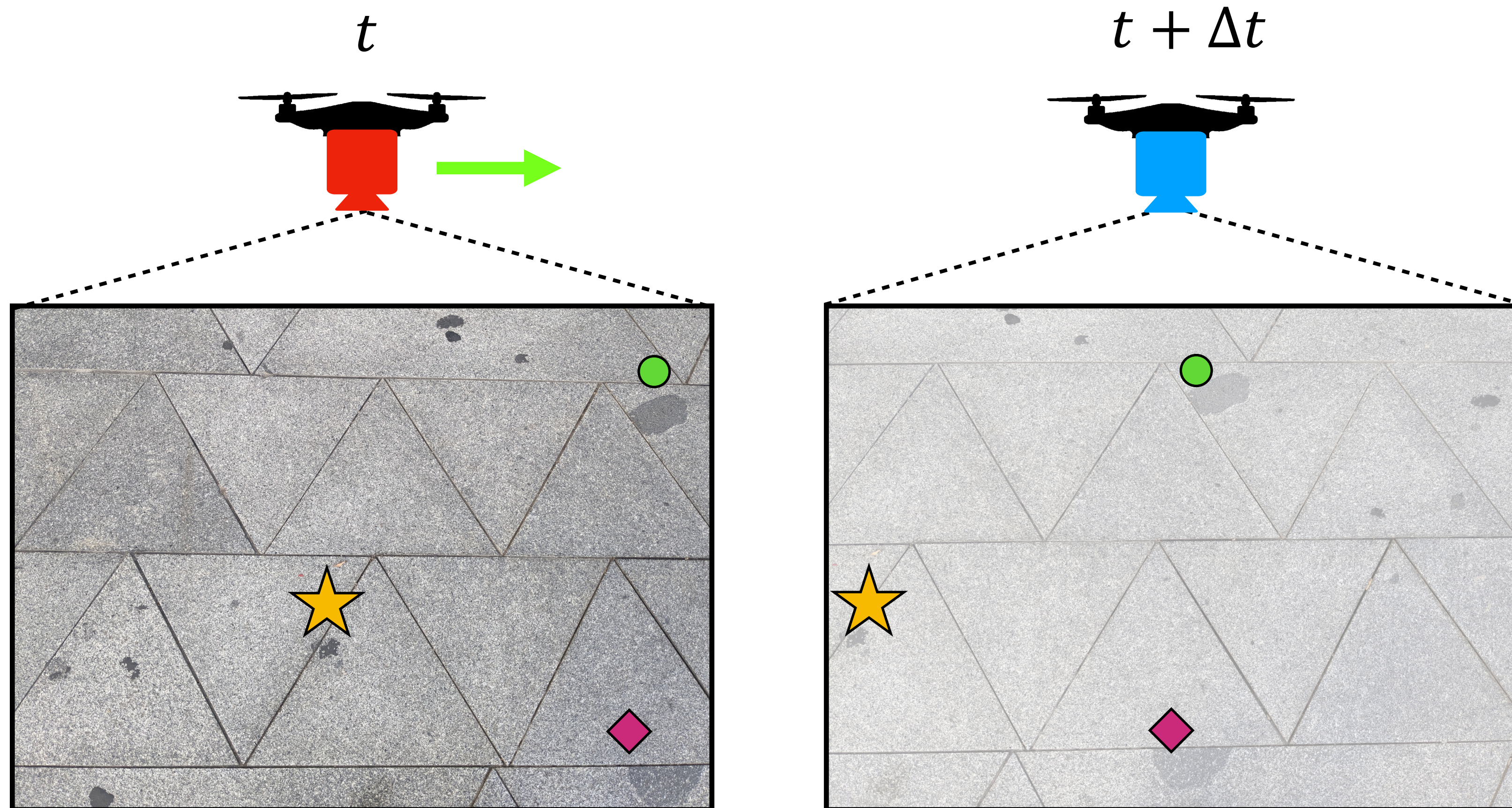
This Talk: Stabilize the Drone with 1 Radar



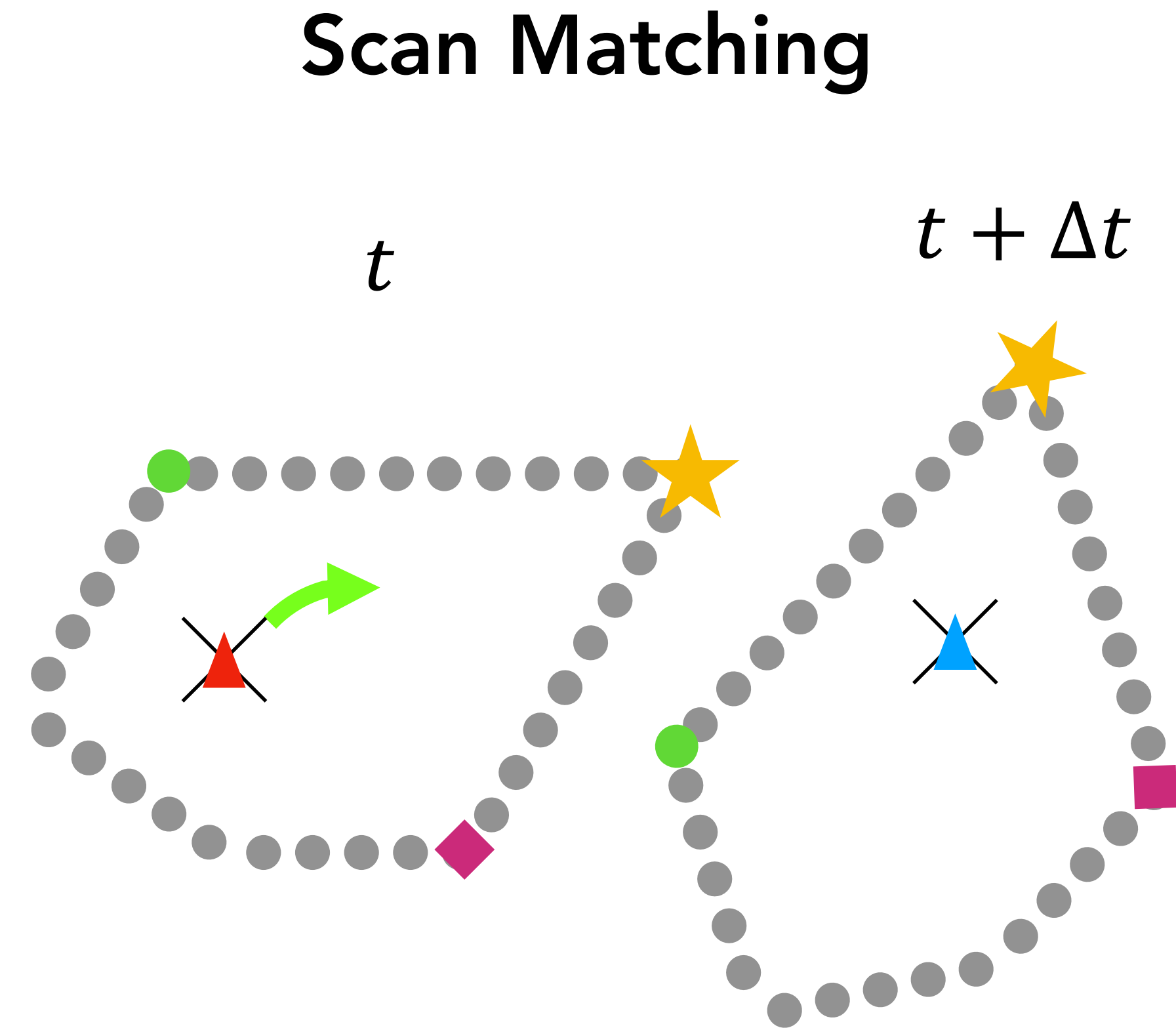
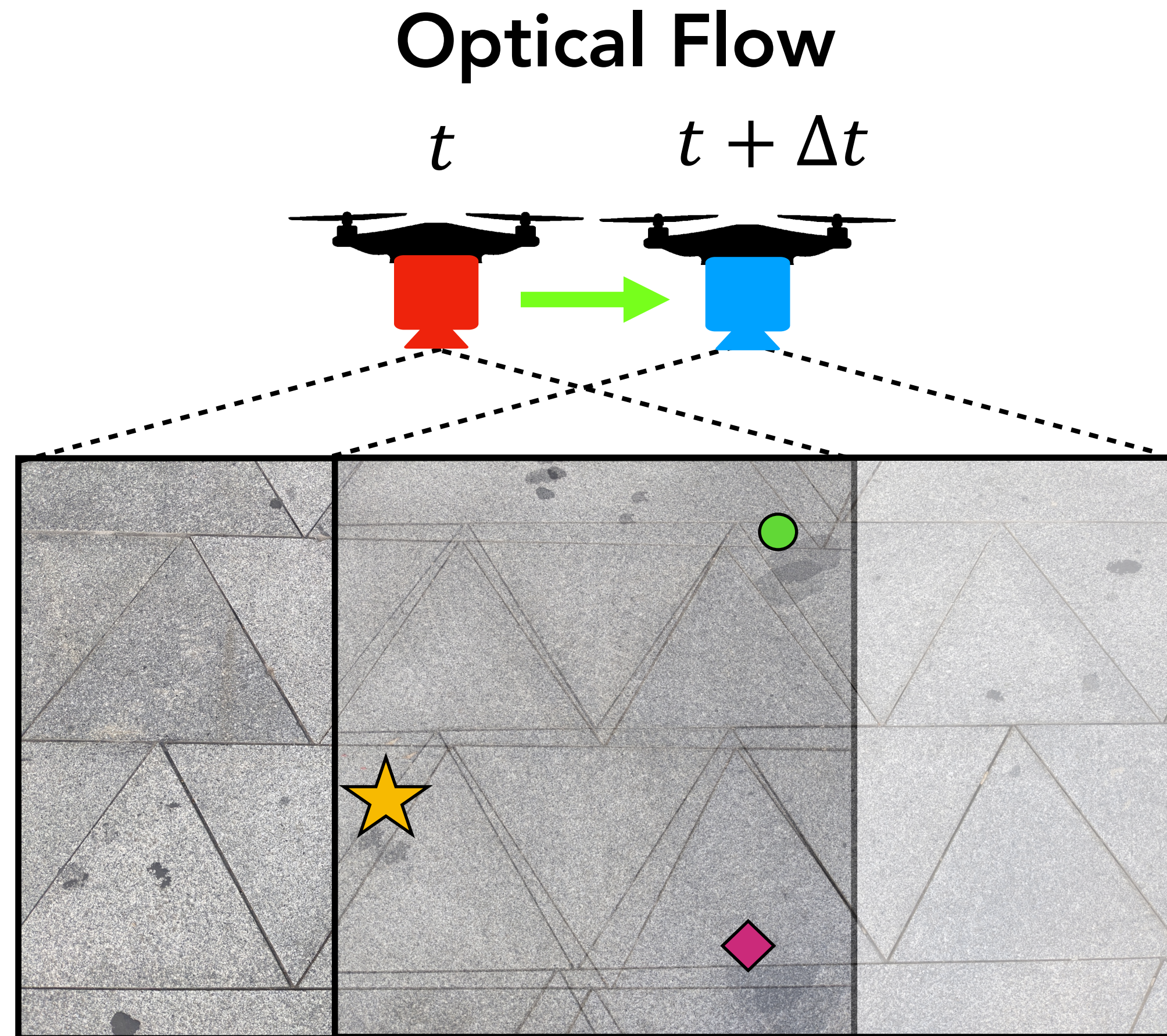
How to get ground velocity from radar?

Optical Methods Rely on Correspondences

Optical Flow

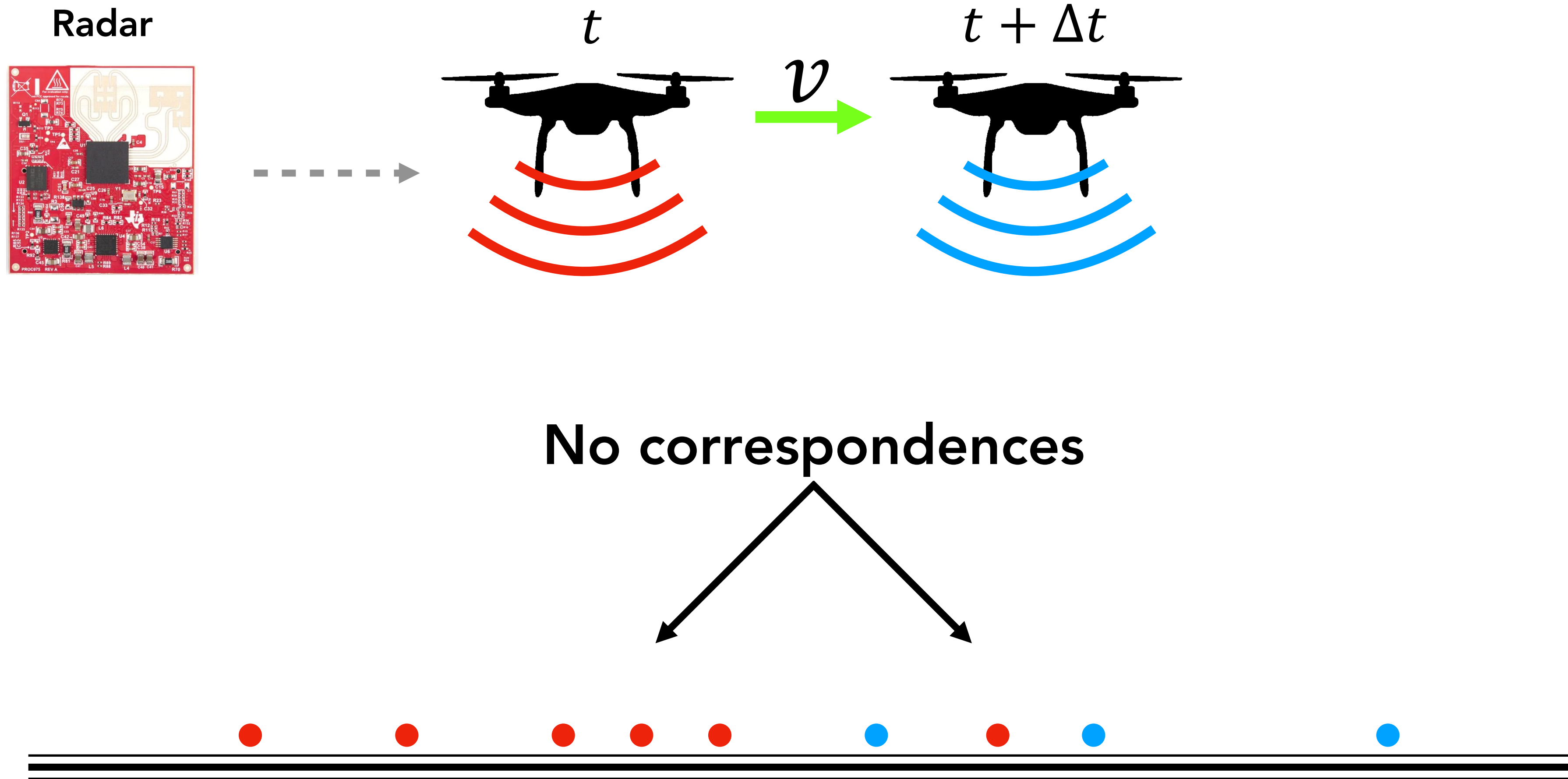


Optical Methods Rely on Correspondences

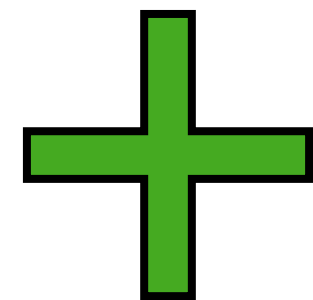


Works very well with optical sensors!

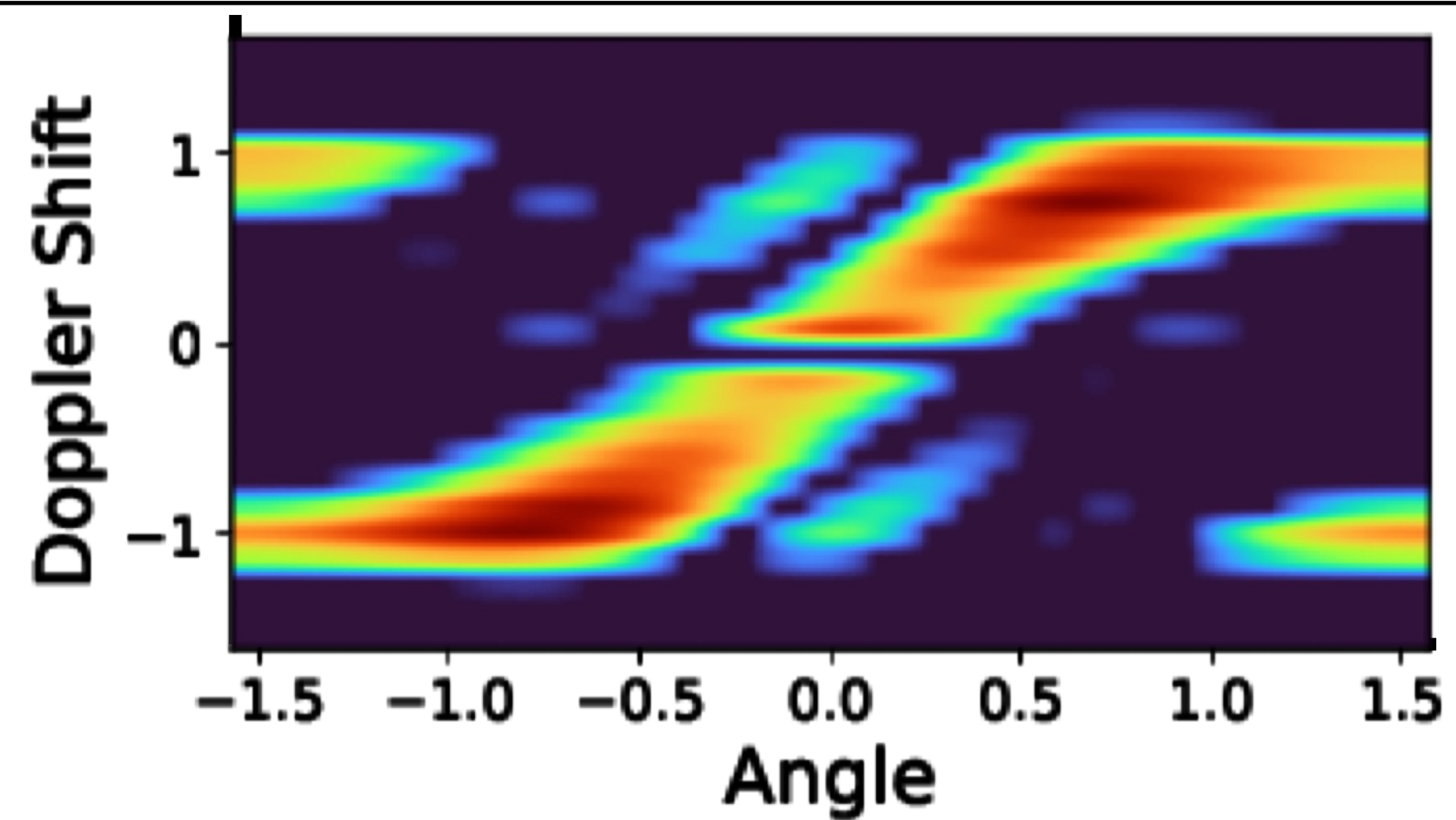
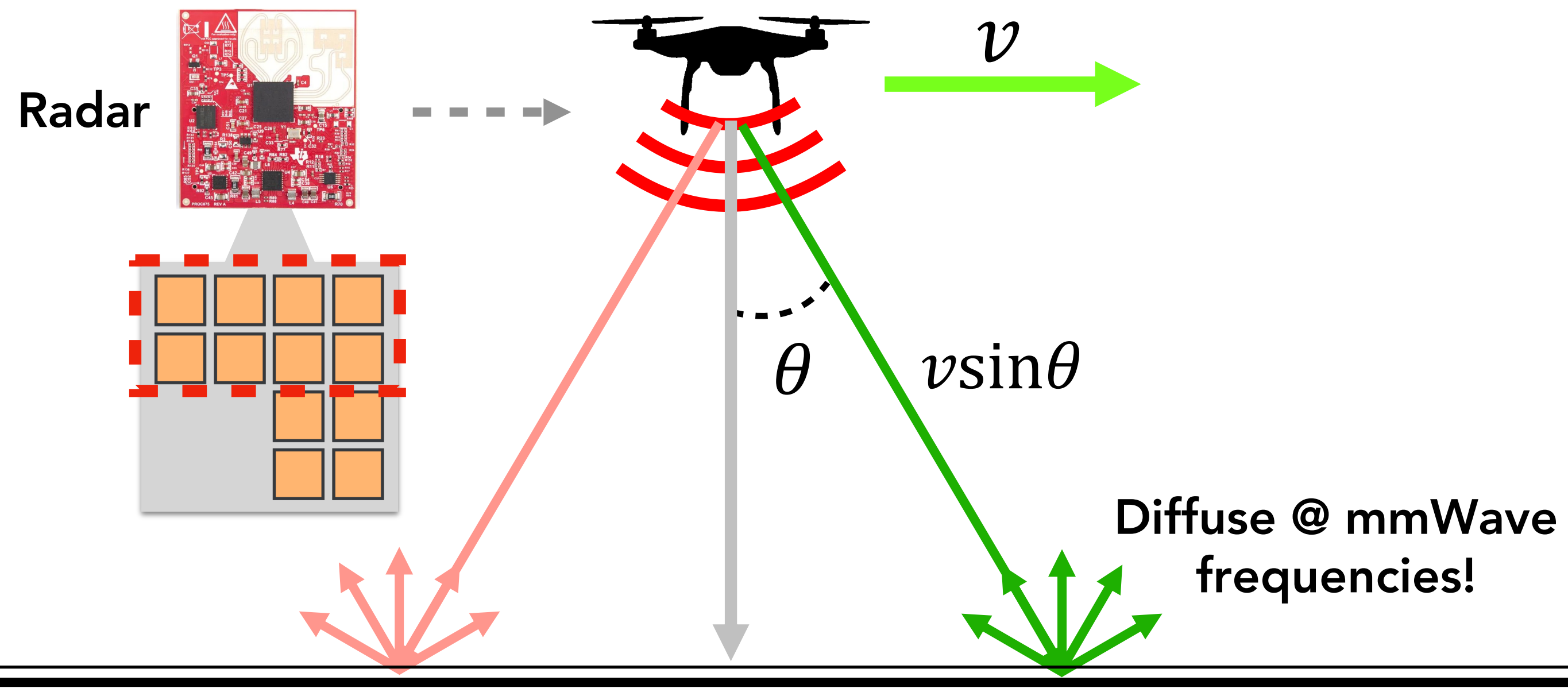
Why doesn't this work with radar?



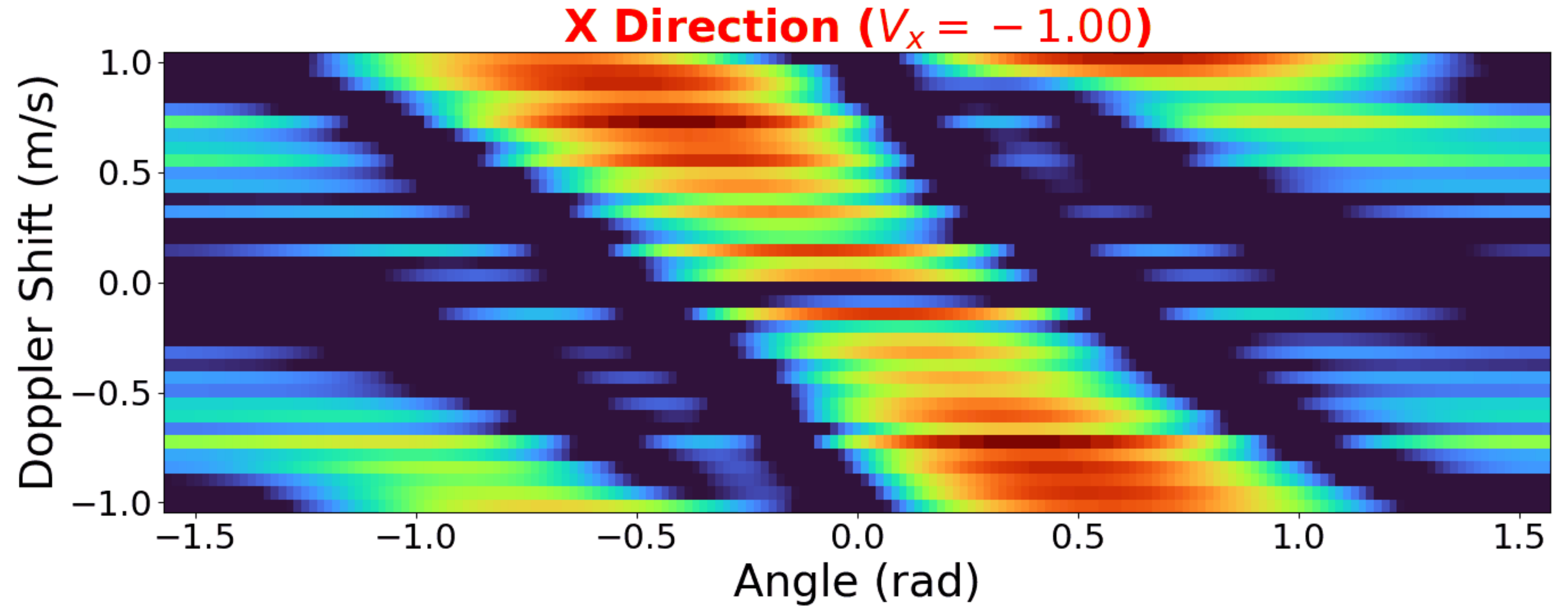
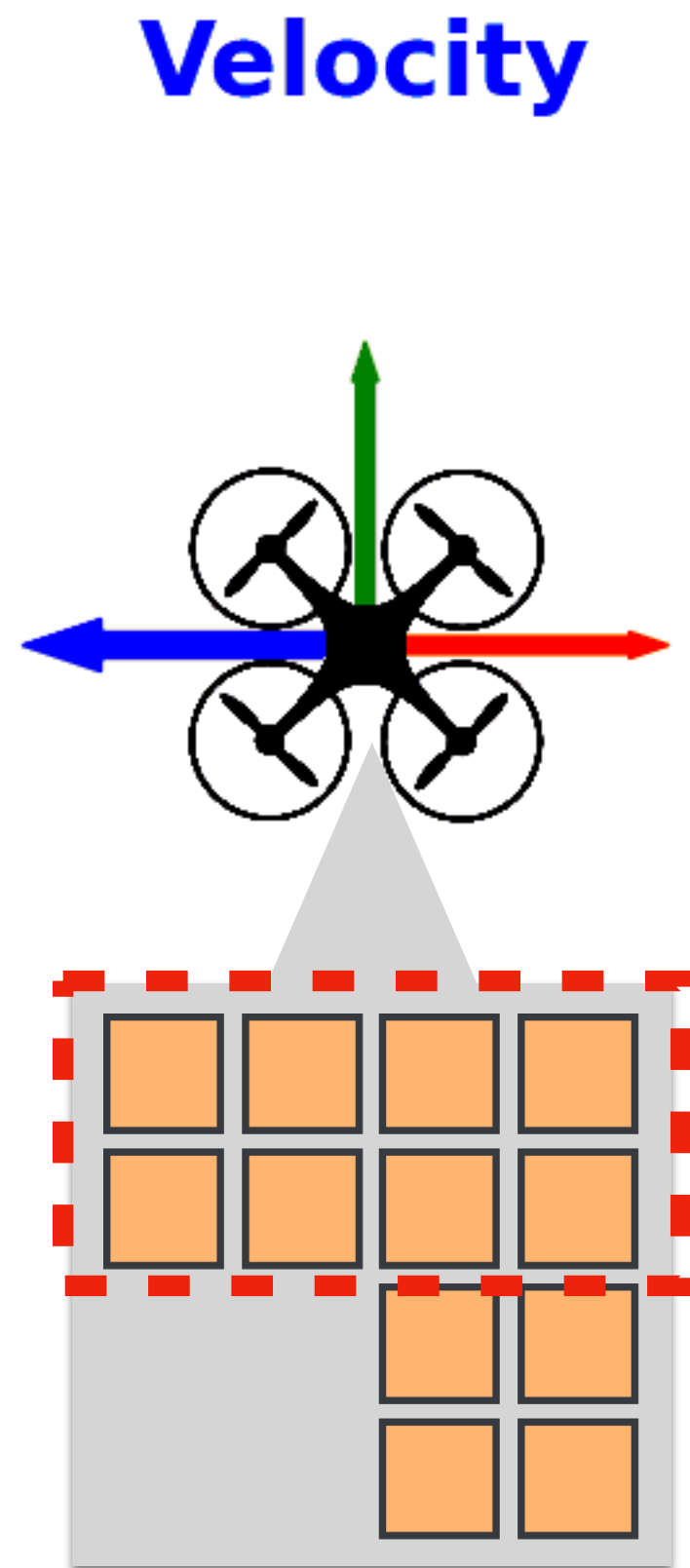
Our Approach: Doppler Shift



Surface-Parallel Doppler Shift

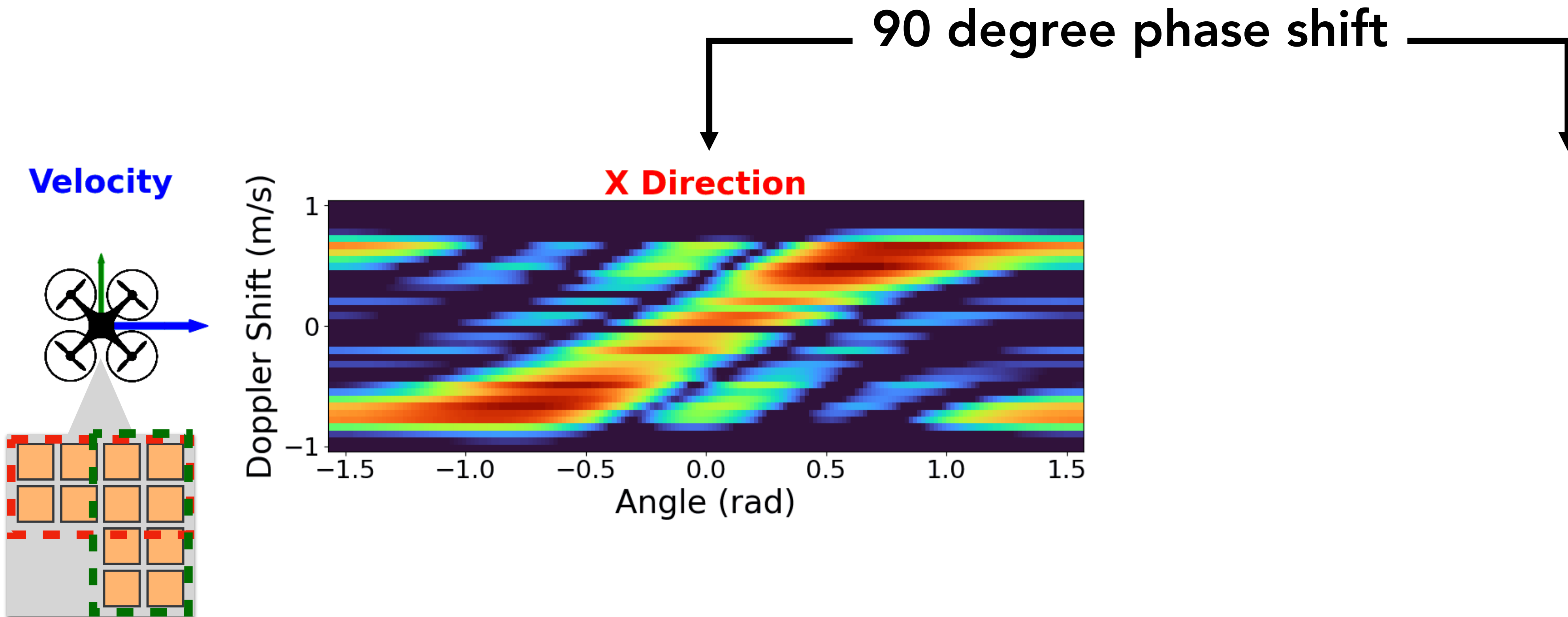


Surface-Parallel Doppler Shift



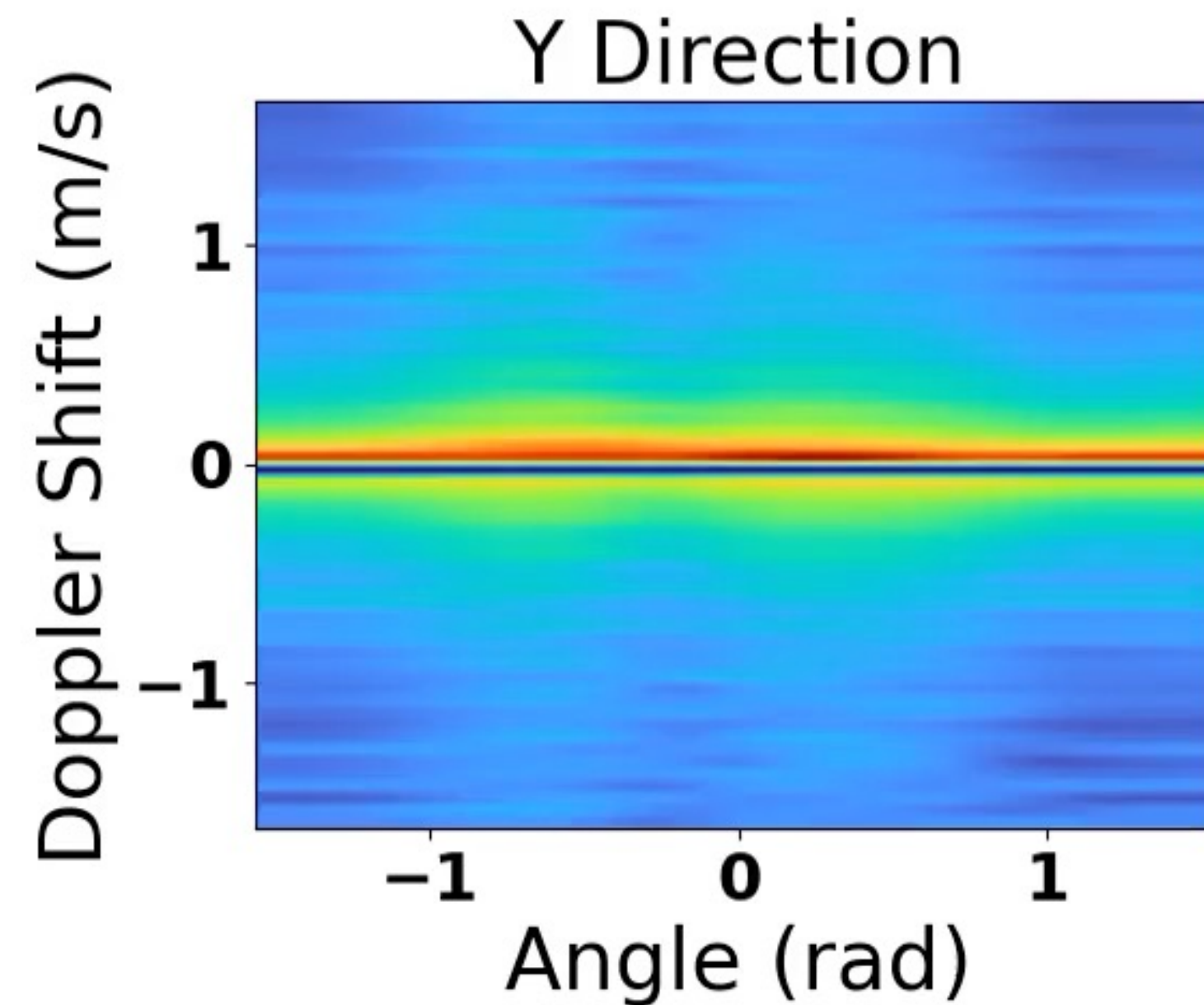
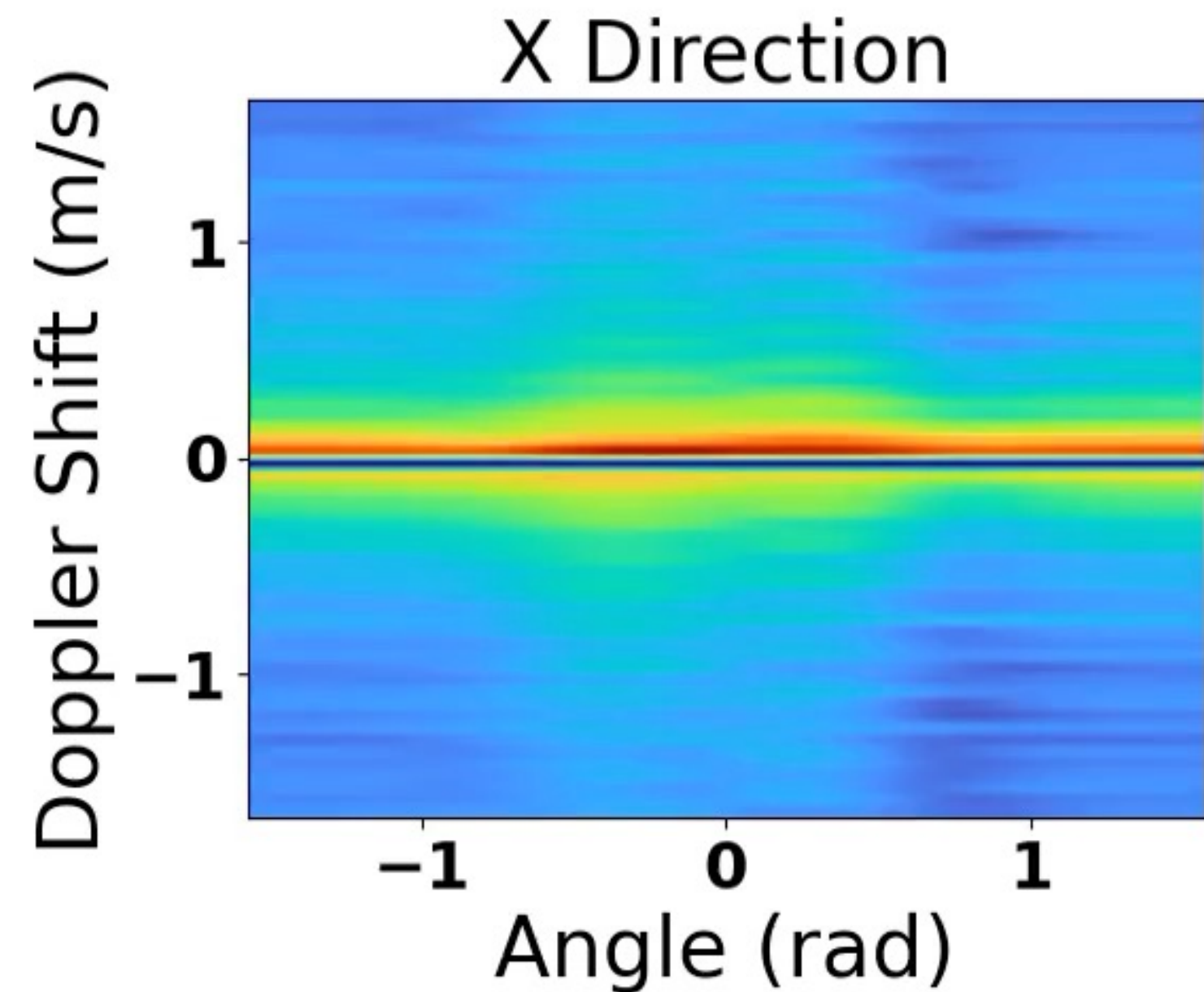
Magnitude correlated with velocity

Surface-Parallel Doppler Shift



Combine X and Y to find 2D velocity

What does it look like in reality?



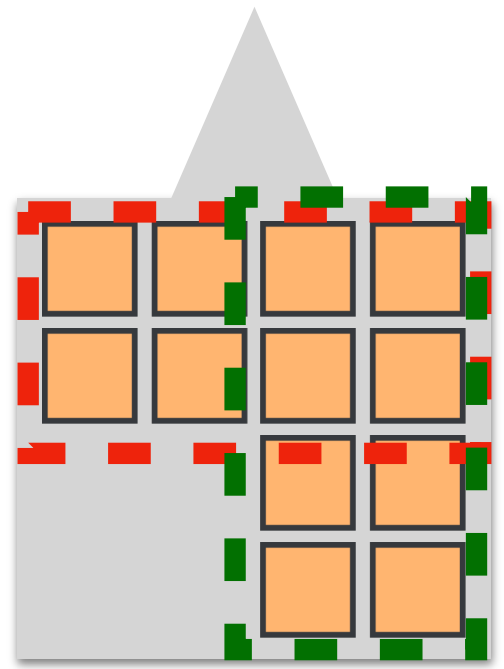
Heatmaps cluttered by

- Noise
- Multipath
- Surface Reflectivity
- Surface Specularity

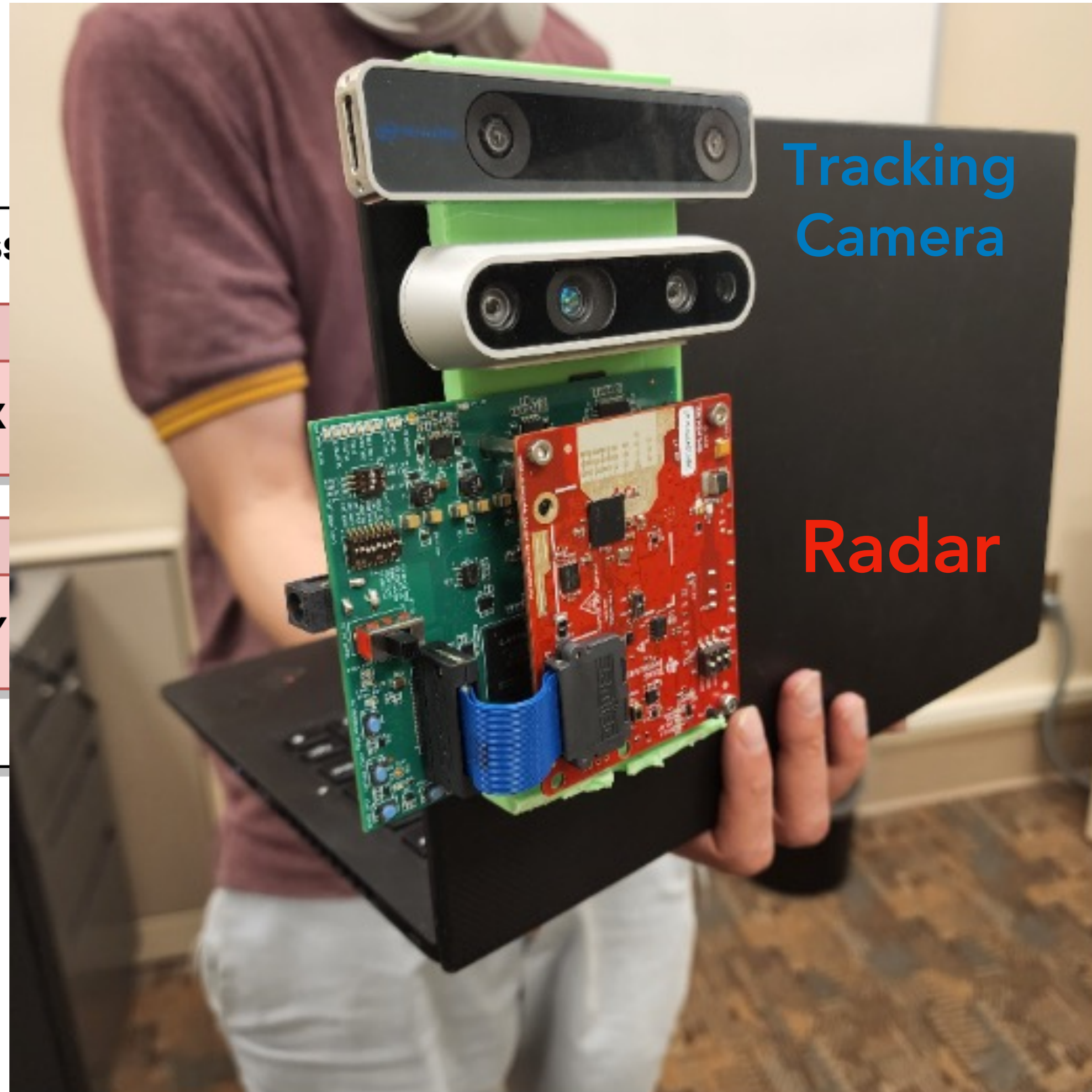
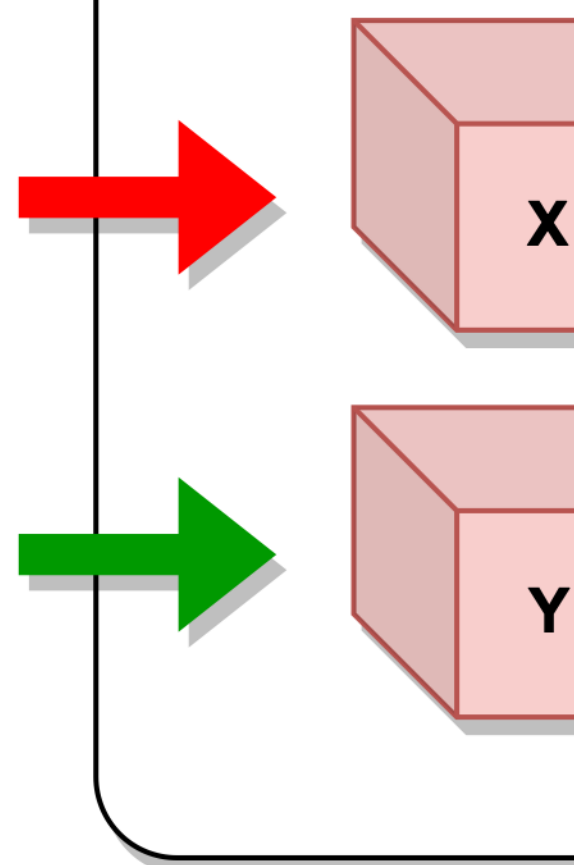
Need some way to cut through the clutter

Radio Flow CNN

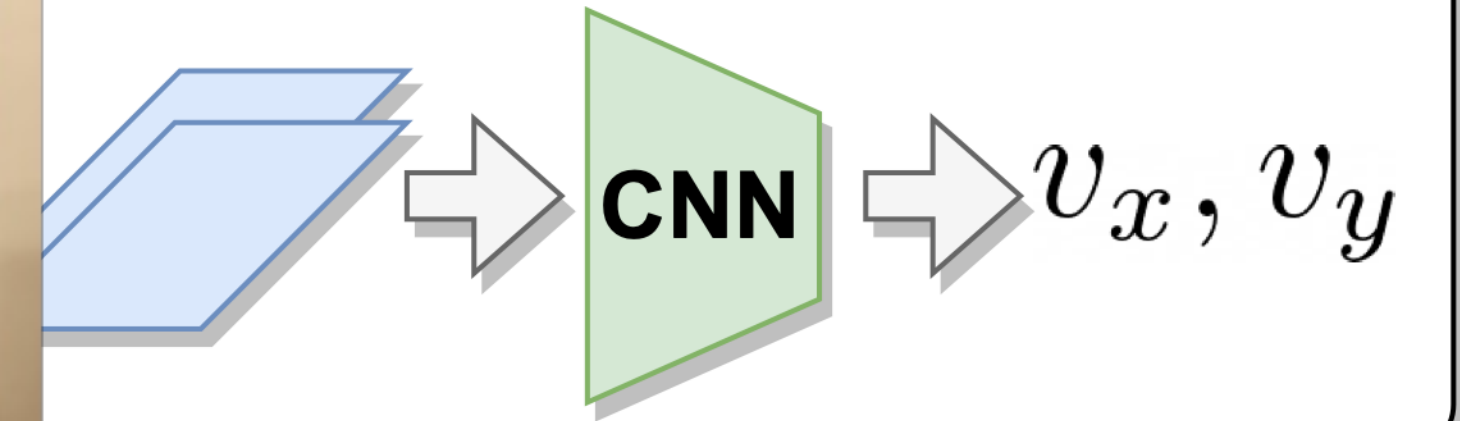
Antenna Array



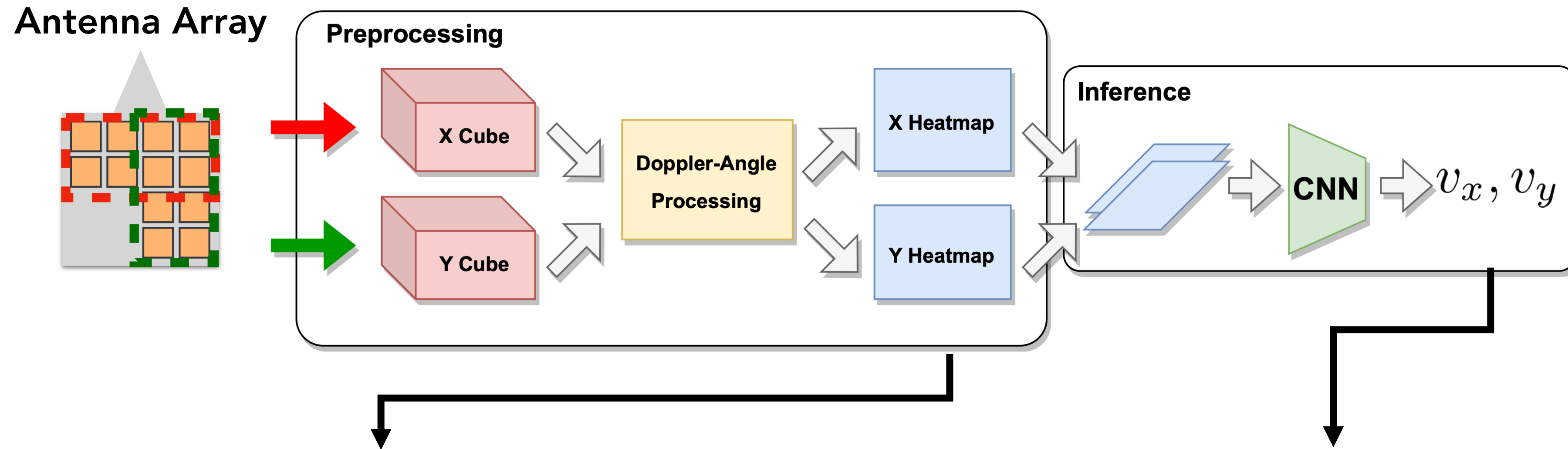
Preprocess



ference

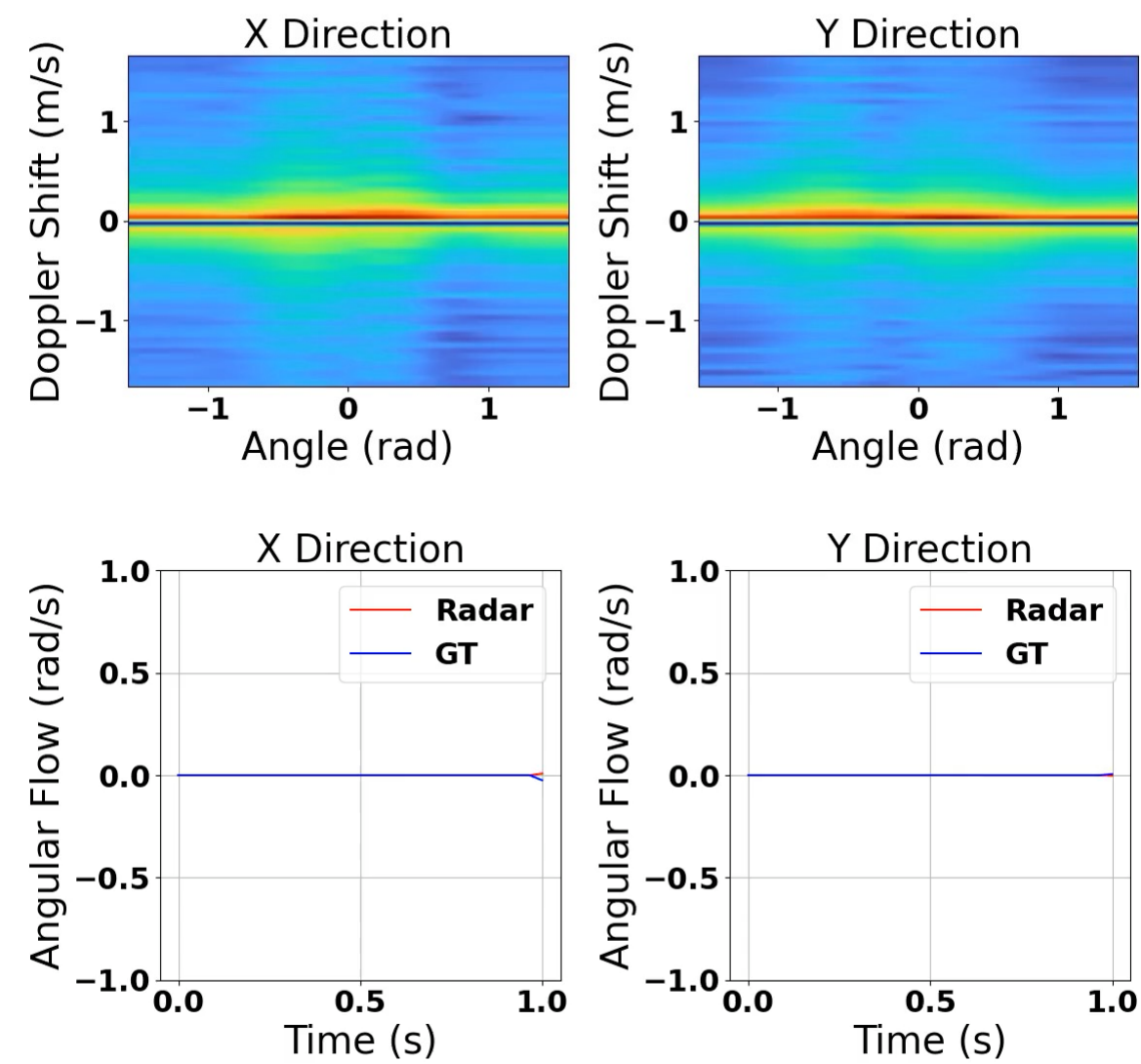


Radio Flow CNN



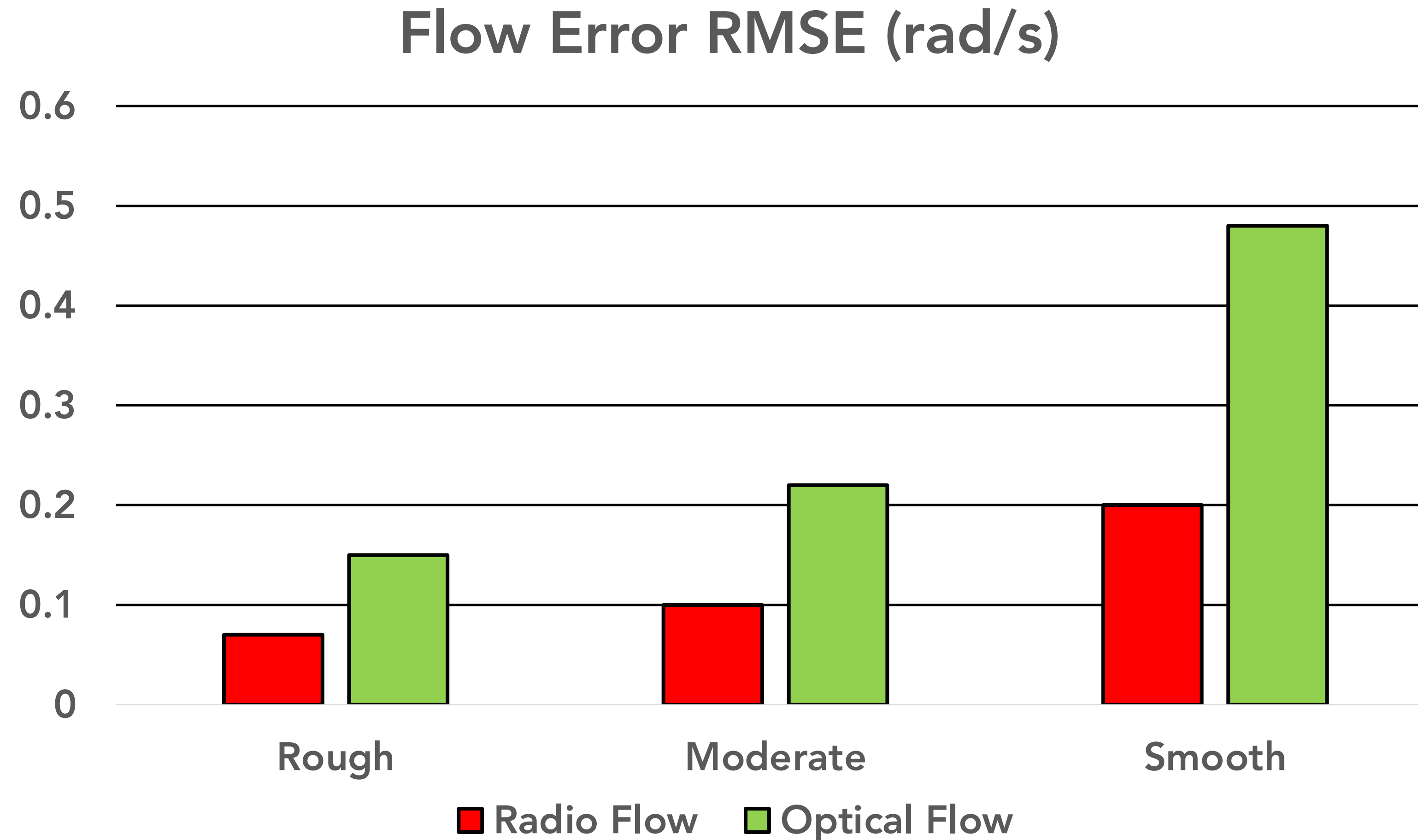
Does this generalize across surfaces?

Grass



Difficulty increases with surface smoothness

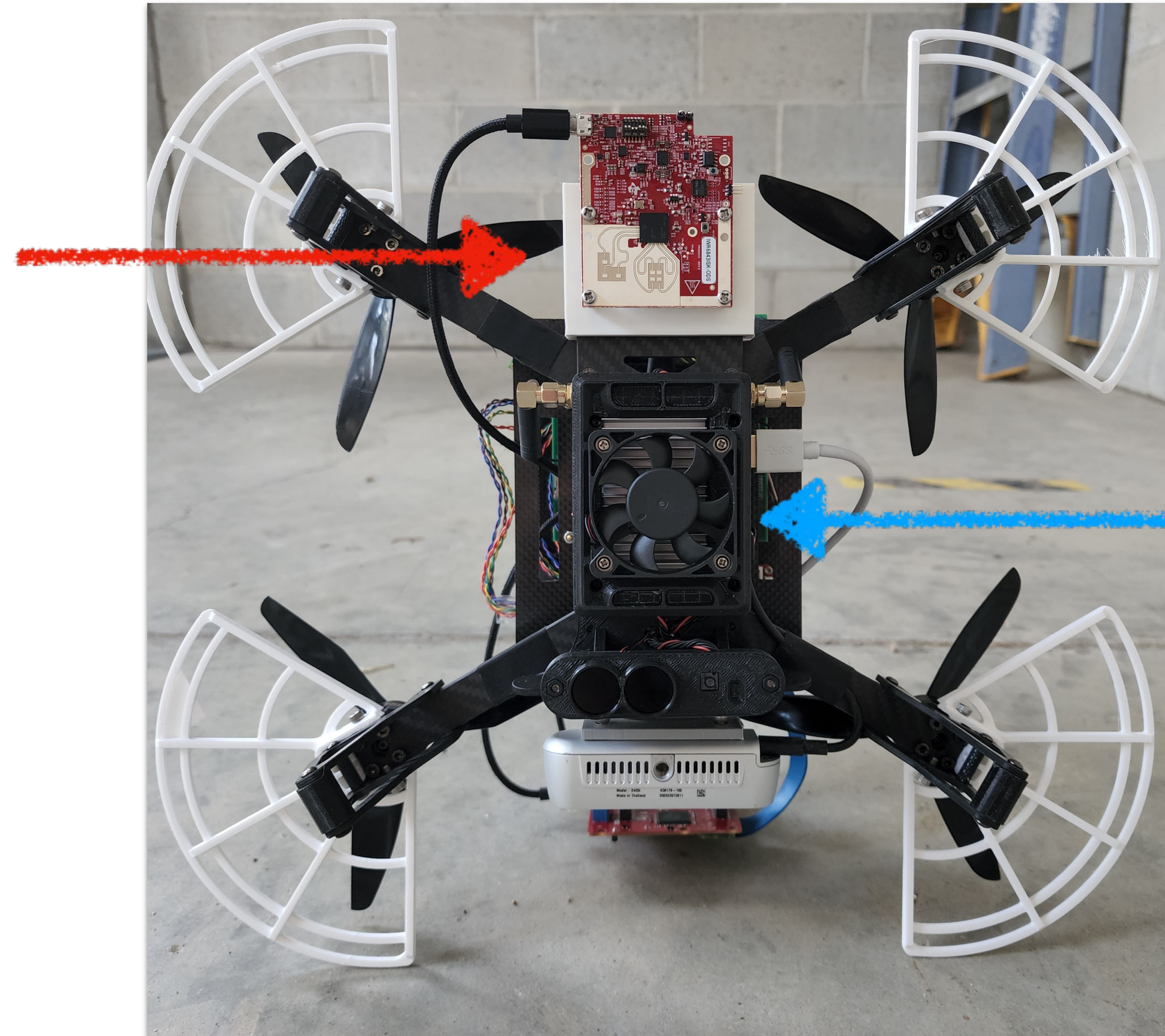
Does this generalize across surfaces?



Difficulty increases with surface smoothness

Plug-and-play into off-the-shelf drone

Overhead
Radar



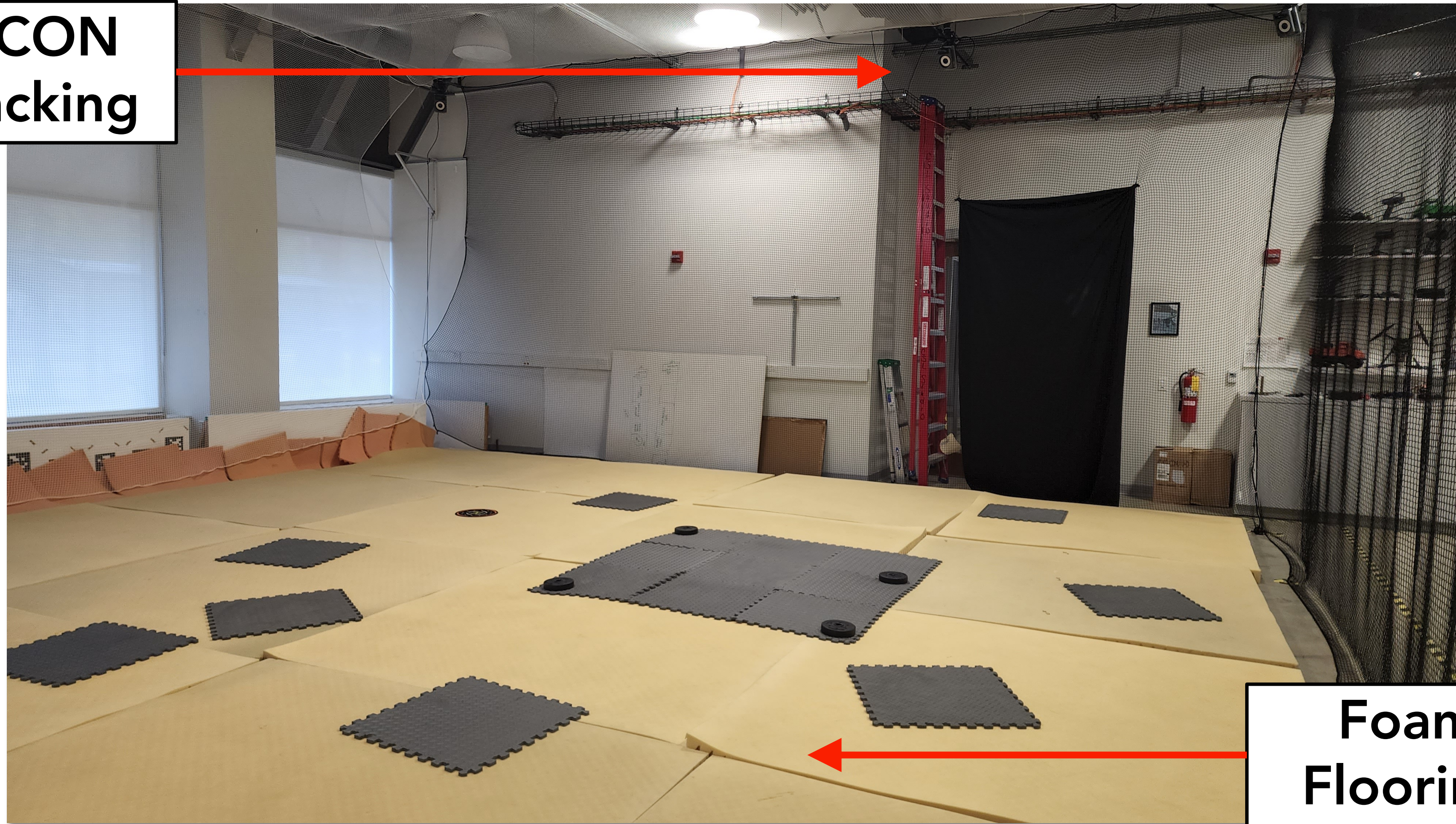
Intel Up Board

- Intel Atom x5-Z8350 (QuadCore 1.44Ghz)
- 4 GB RAM

Runs up to 40Hz on on-board CPU core

Hover Test

VICON
Tracking

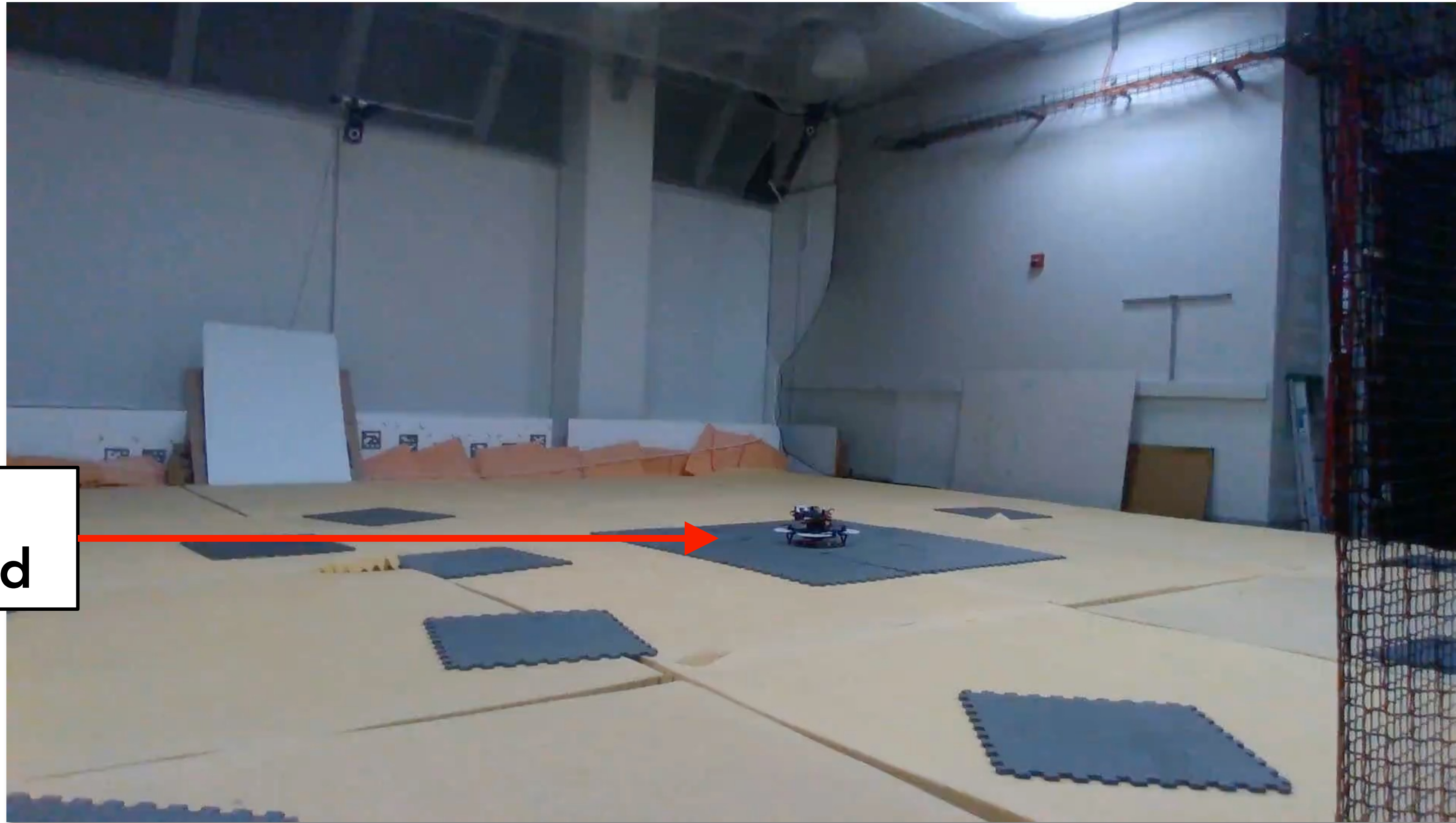


Foam
Flooring

Fly drone to fixed height, measure horizontal drift



Optical Flow (Baseline)



Patterned
Landing Pad





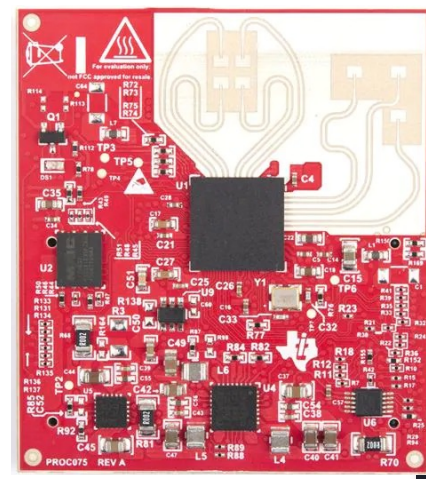
Optical Flow (Featureless)



Radio Flow (Featureless)

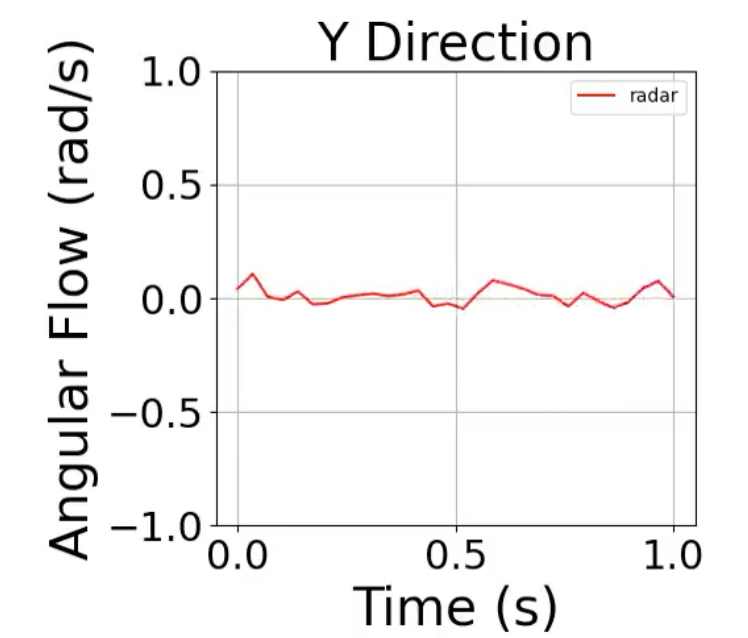
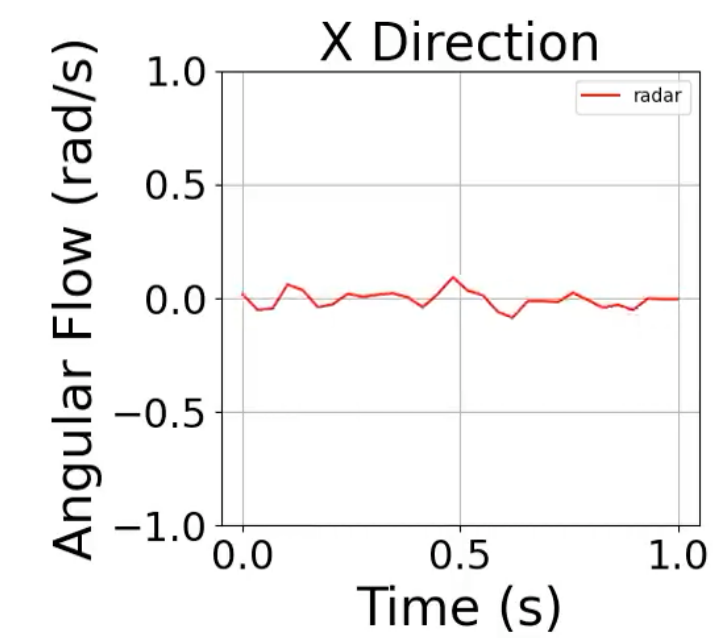
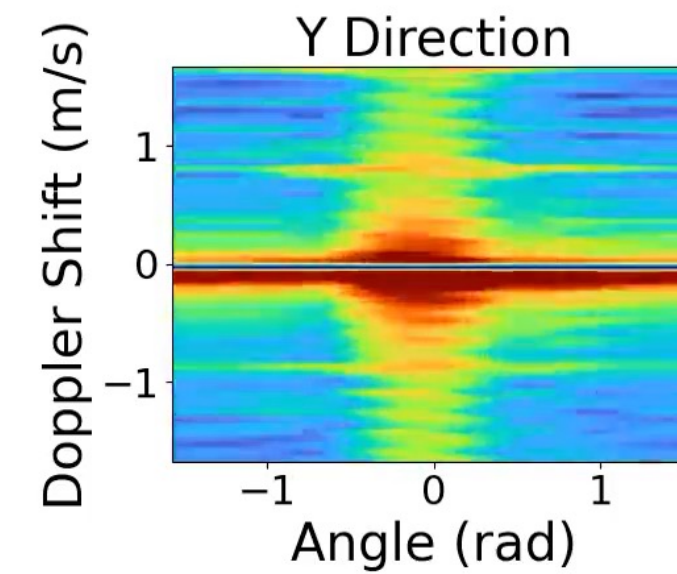
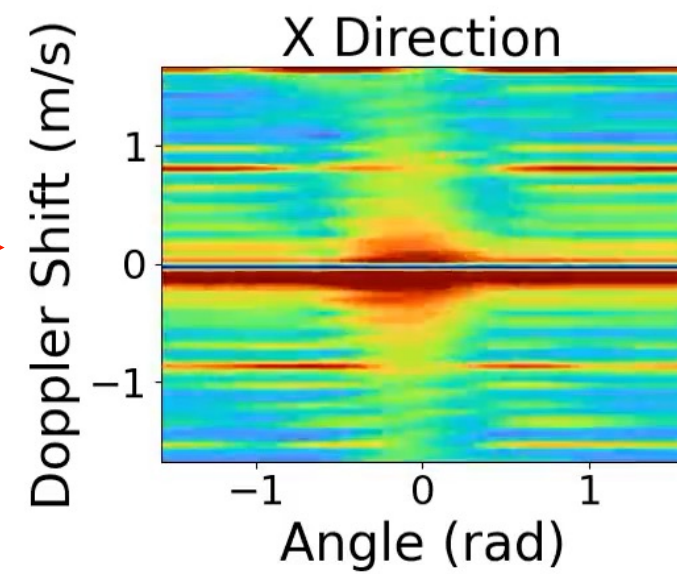


Optical Flow



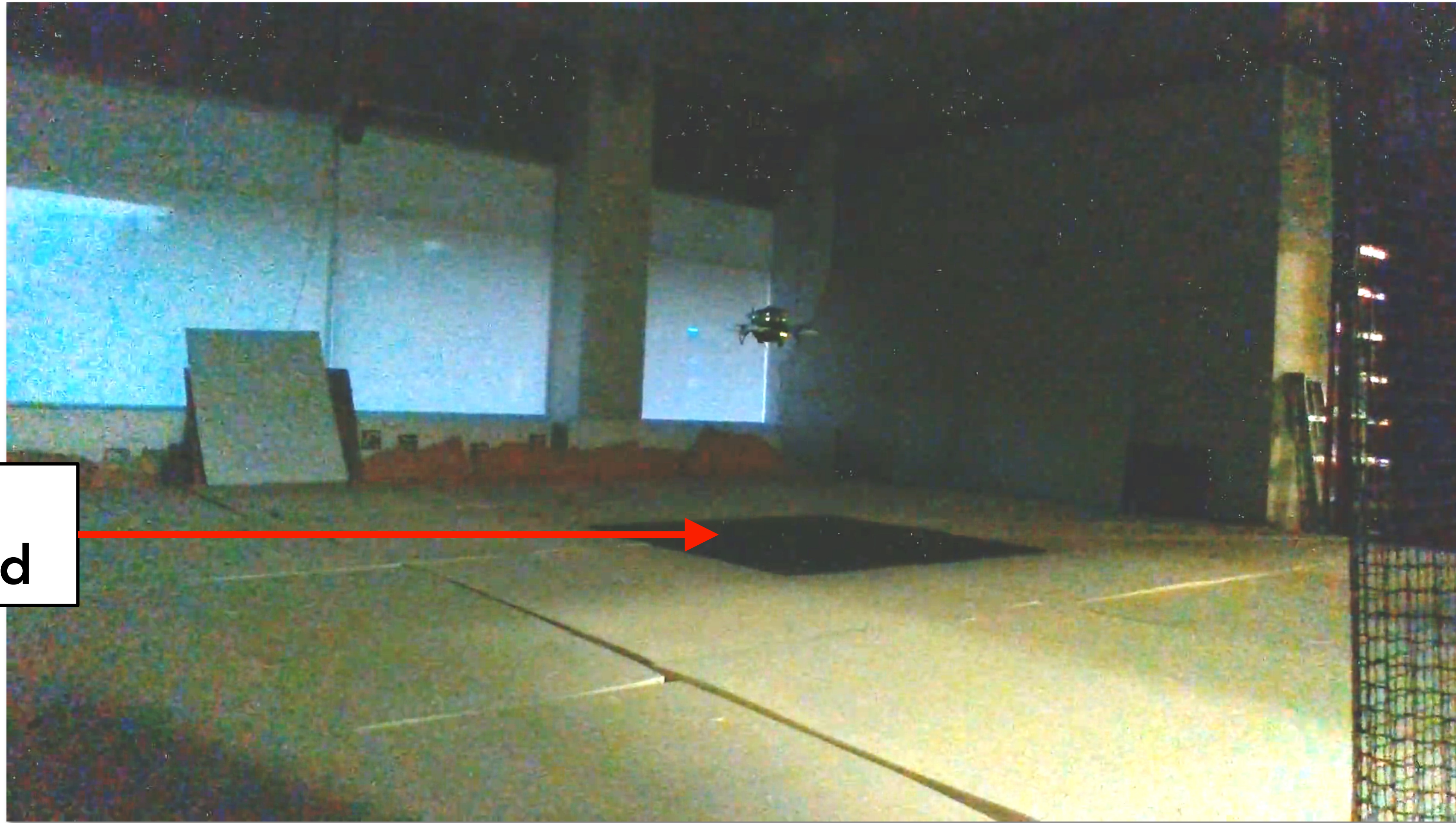
Foam Floor

- Looks smooth to radar
- Not in training set





Optical Flow (Dark)



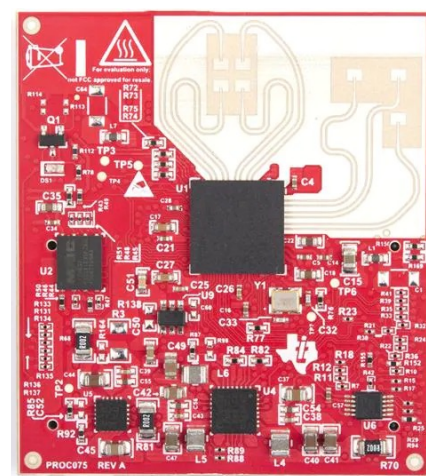
**Patterned
Landing Pad**



Radio Flow (Dark)

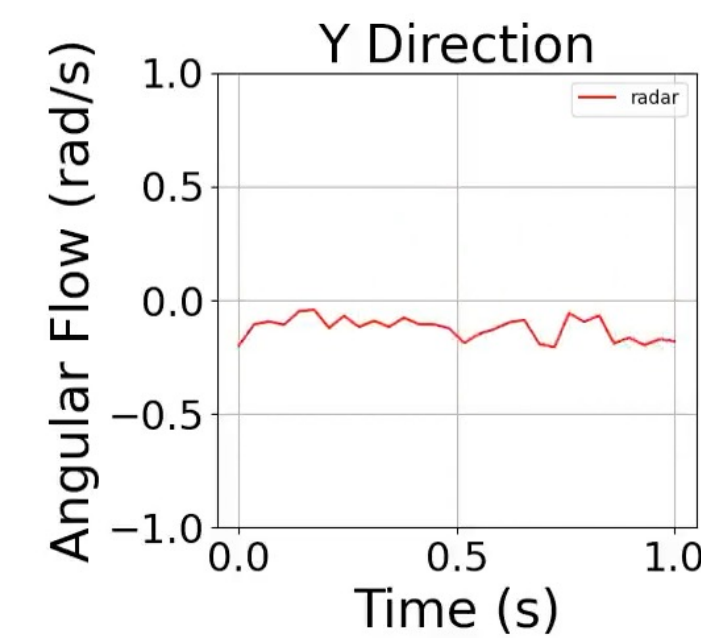
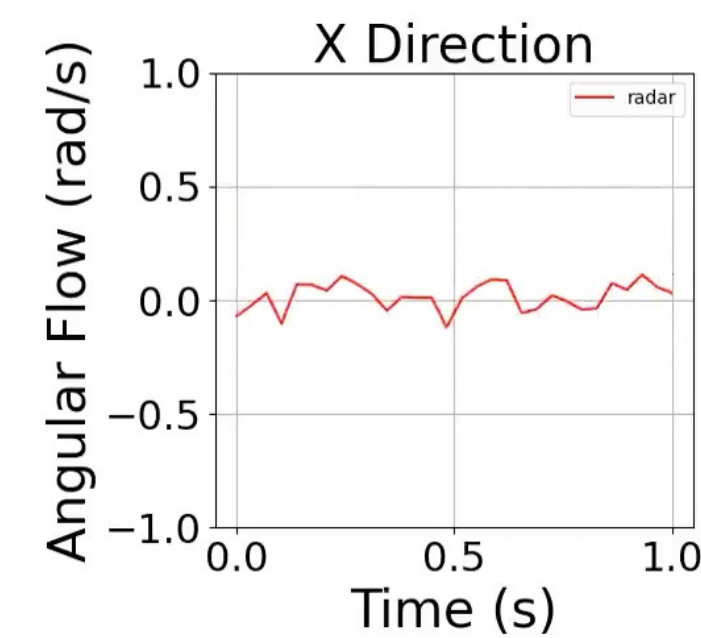
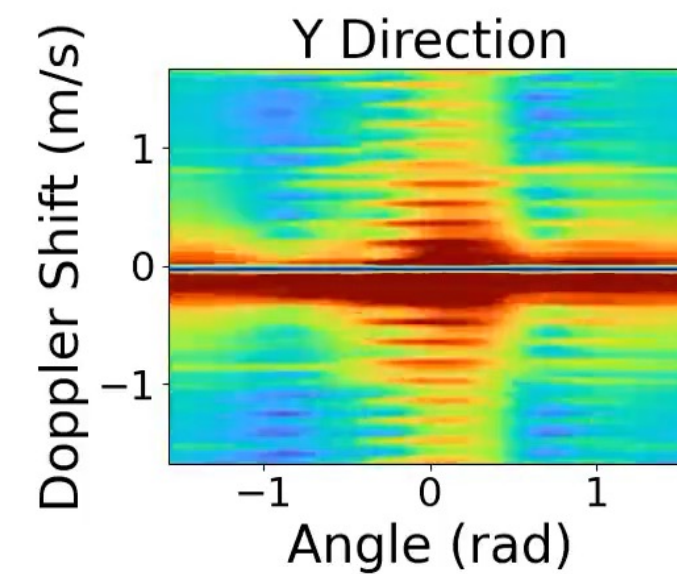
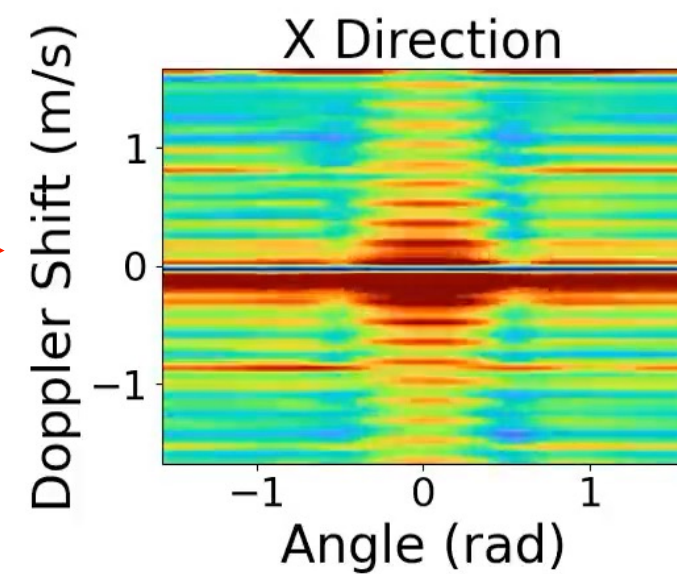


Optical Flow

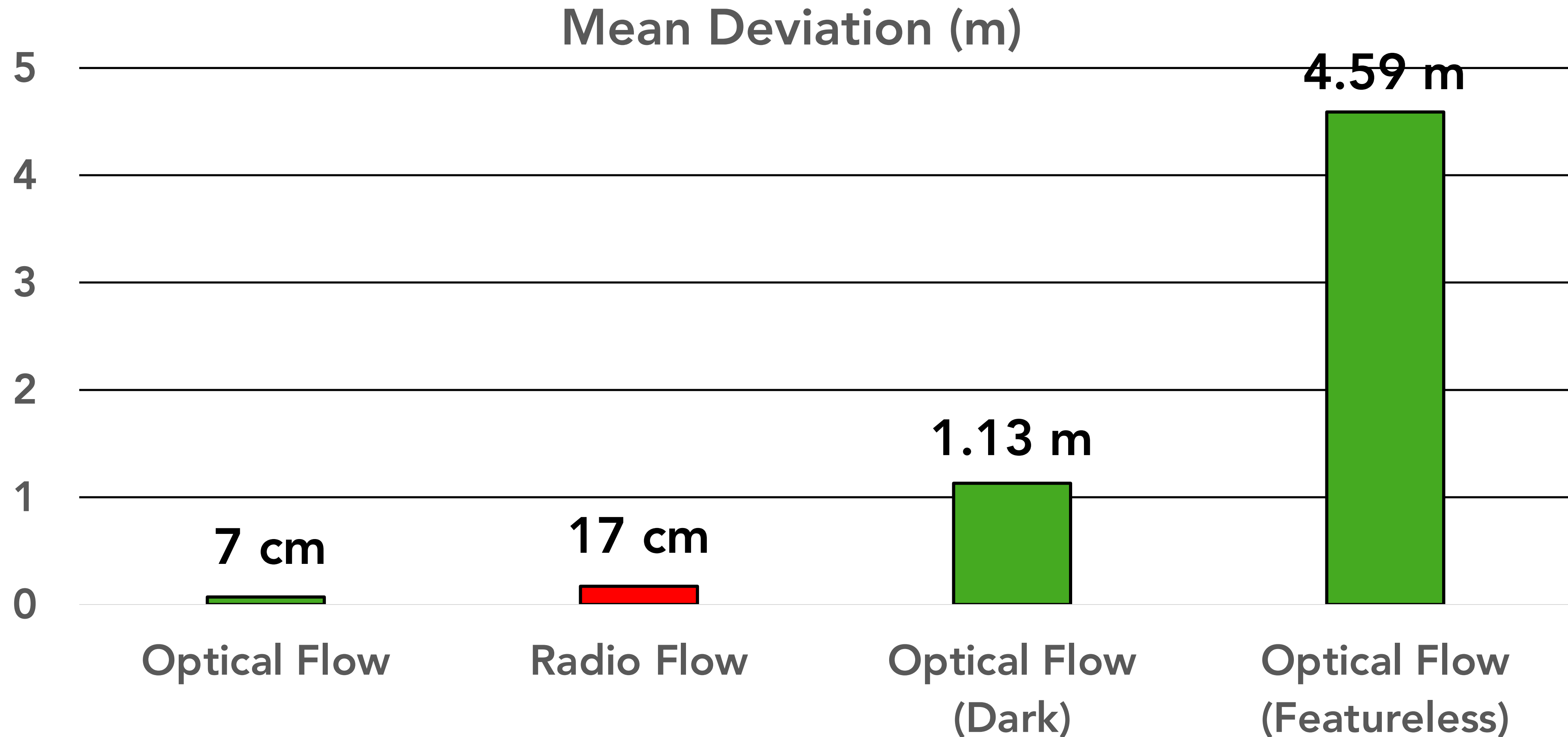


Foam Floor

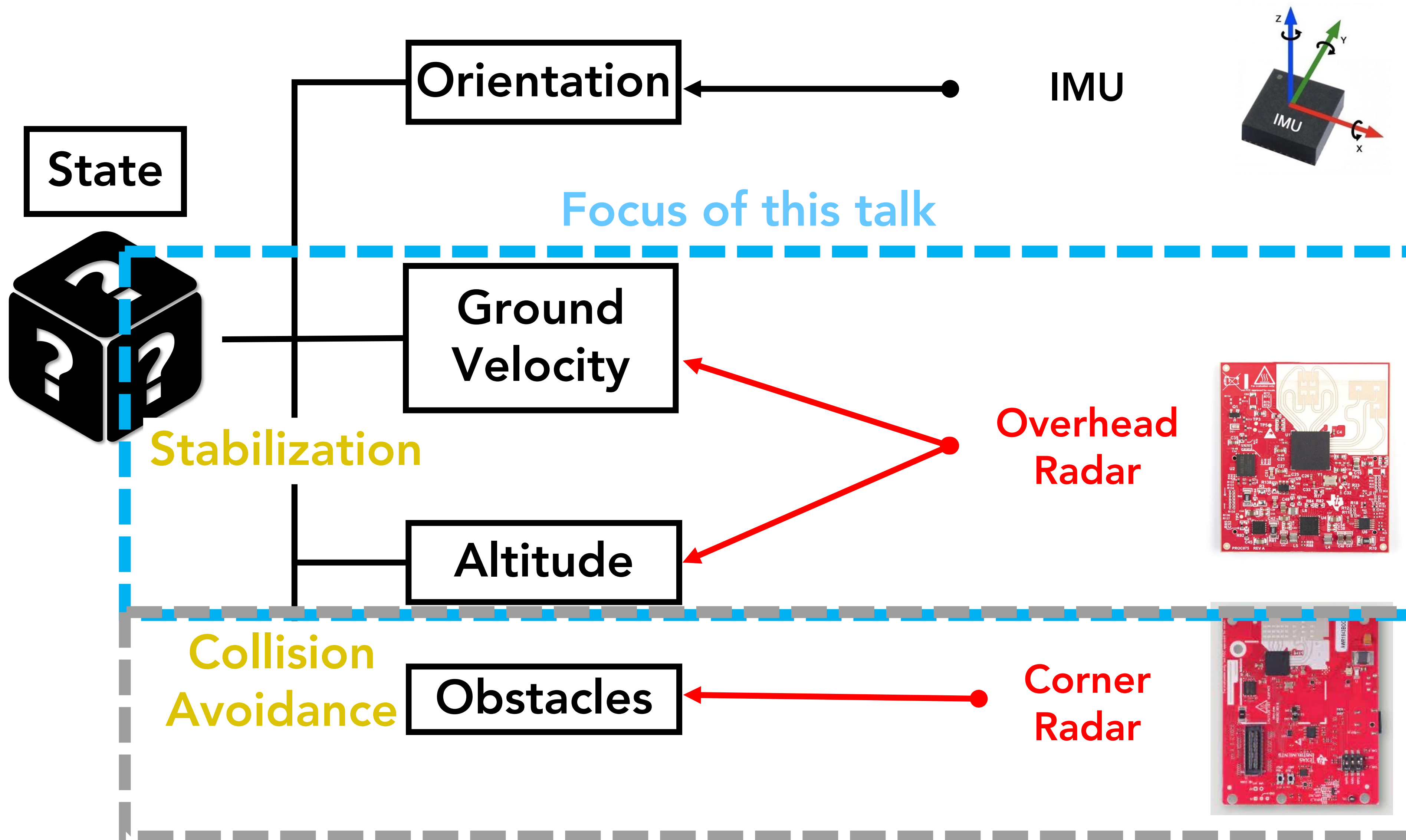
- Looks smooth to radar
- Not in training set



How does radio flow stack up?



BatMobility Overview



More demos, code, data available at project website

batmobility.github.io



- We identify the phenomenon of *surface-parallel doppler shift* at mmWave frequencies.
- We introduce *radio flow* which is more robust than optical flow.
- We demonstrate radio flow as a *plug-and-play module* on an off-the-shelf drone.

